

# Vess A6600 (VES0603) Vess A6800 (VES0604) Storage Appliance for Video Surveillance Product Manual

Version 1.0

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Also included are four levels of notices:



### Warning

A Warning notifies you of probable equipment damage or loss of data, or the possibility of physical injury, and how to avoid them.



### Caution

A Caution informs you of possible equipment damage or loss of data and how to avoid them.



#### Important

An Important message calls attention to an essential step or point required to complete a task, including things often missed.



#### Note

A Note provides helpful information such as hints or alternative ways of doing a task.



## Warning

Turn off the power and disconnect the power cord before servicing this device.



## Warning

The electronic components within the Vess A6000 Series enclosure is sensitive to damage from Electro-Static Discharge (ESD). Observe appropriate precautions at all times when handling the Vess A6000 or its subassemblies.



### Warning

- Use an approved power cord. If you have questions about the type of power cord to use, contact your PROMISE Technology, Inc. authorized service provider.
- If you have not been provided with a power cord for your product or for any AC-powered option intended for your product, purchase a power cord that is approved for use in your country.
- You must use a power cord rated for your product and for the voltage and current marked on the electrical ratings label of the product. The voltage and current rating of the cord must be greater than the voltage and current rating marked on the product.
- Do not pull on a cord or cable. When unplugging from the electrical outlet, grasp the cord by the plug.
- Make sure that the total ampere rating of all products plugged into an extension cord or power strip does not exceed 80 percent of the ampere ratings limit for the extension cord or power strip.
- Do not disable the power cord grounding plug. The grounding plug is an important safety feature.
- Plug the power cord into a grounded (earthed) electrical outlet that is easily accessible at all times.
- Only a qualified technician who is familiar with fix up service procedure should install and service the equipment.
- Verify that the external power source connected to your product matches the type of power source indicated on the electrical ratings label. If you are not sure of the type of power source required, consult your PROMISE Technology, Inc. authorized service provider or local power company.



為減少電擊或設備損壞的危險:

- 使用認可的電源線。如果您對使用的電源線類型有疑問,請聯繫喬鼎資訊授權的服務提供商。
- 如果沒有為您的產品或任何預期的交流電供電選項提供電源線對於您的產品,請購買經批准在您所在 國家使用的電源線。
- 您必須使用適用於您的產品的電源線以及電氣上標註的電壓和電流產品的評級標籤。電源線的電壓 和電流額定值必須大於電壓和產品上標明的電流額定值。
- 請勿拉扯電線或電纜。 從電源插座上拔下插頭時,請抓住電源線。
- 確保所有插入延長線或配電盤的產品的總額定電流值不超過延長線或電源插座的安培額定值的80%。
- 請勿禁用電源線接地插頭。 接地插頭是一個重要的安全功能。
- 將電源線插入隨時可輕鬆接地的接地(接地)電源插座。
- 只有熟悉維修程序的合格技術人員才能安裝和維修設備。

如果您不確定所需的電源類型,請諮詢喬鼎資訊授權的服務提供商或當地的電力公司。

### **Federal Communications Commission notice**

#### **Class A equipment**

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to Part 15 of the FCC rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference, in which case the user will be required to correct the interference at personal expense

#### Modification

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

## Industry Canada Regulatory Compliance Notices Avis de conformité à la réglementation d'Industrie Canada

This Class A digital apparatus complies with Canadian ICES-003.

Cet appareil numérique de la classe A est conforme à la norme NMB-003 du Canada.

### Notices for New Zealand and Australia

#### **Class A equipment**

This is a Class A product. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

### **Notices for European Union**

This product is in conformity with the protection requirements of EU Council Directive 2014/30/EU on the approximation of the laws of the Member States relating to electromagnetic compatibility. PROMSIE Technology, INC. cannot accept responsibility for any failure to satisfy the protection requirements resulting from a non-recommended modification of the product, including the fitting of non-PROMISE option cards.

This product has been tested and found to comply with the limits for Class A Information Technology Equipment according to CISPR 32/European Standard EN 55032. The limits for Class A equipment were derived for commercial and industrial environments to provide reasonable protection against interference with licensed communication equipment.

This is a Class A product. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

The point of contact for regulatory matters is PROMISE TECHNOLOGY EMEA, Science Park Eindhoven 5228, 5692 EG Son, The Netherlands.

Office Hours

8:30 am - 5:00 pm (The Netherlands)

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A급기기	이 기기는 업무용 환경에서 사용할 목적으로
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這是甲類的資訊產品,在居住的環境中使用時,可能會造成射頻干擾,在這種情況下,使用者 會被要求採取某些適當的對策。

設備名稱:磁碟陣列儲存系統型號(型式): VES0603、VES0604			0604			
Equipment name Type designation (Type)						
單元Unit	單元Unit 限用物質及其化學符號					
	Restrict	ted substa	nces and	its chemical	l symbols	
		Ŧ	1-	六價鉻	多溴聯苯	多溴二苯醚
	鉛Lead	汞	鎘		Polybrominated	Polybrominated
	(Pb)	Mercury	Cadmium	chromium	biphenyls	diphenyl
	(1.07	(Hg)	(Cd)	(Cr+6)	(PBB)	ethers (PBDE)
同時に						
電路板		0	0	0	0	0
外殼	—	0	0	0	0	0
線材	0	0	0	0	0	0
電源供應器	—	0	0	0	0	0
電池	—	0	0	0	0	0
	0.1 wt %	"及"超出	30.01 wt	%"係指限用物	物質之百分比含量起	超出百分比含量基
準值。						
Note 1: "Ex	ceeding	0.1 wt %"	and "e	xceeding 0.0	1 wt % " indicat	e that the
percentage c	ontent o	f the rest	tricted s	ubstance exc	eeds the referen	ce percentage
value of pre	sence co	ndition.				
備考2. "○"係指該項限用物質之百分比含量未超出百分比含量基準值。						
Note 2: "O" indicates that the percentage content of the restricted substance						
does not exceed the percentage of reference value of presence.						
備考3. "一"係指該項限用物質為排除項目。						
Note 3: The "-" indicates that the restricted substance corresponds to the						
exemption.						

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# INTRODUCTION

The Vess A6000 Series Storage Appliance for Video Surveillance is specially engineered for medium to large scale IP video surveillance deployment. The Vess A6000 Series is ideally suited for continuous surveillance in banks, malls, casinos, factories, warehouses, and similarly sized commercial, residential, governmental or private enterprises. The subsystems are capable of continuous recording and playback operation without dropping frames for networked installations of 64 to 150 High-Definition IP cameras.

Vess A6000 Series Storage Appliance for Video Surveillance are available with the Windows operating system, a Video Management Software suite, and disk drives in order to streamline the installation and integration process. The Vess A6000 Series subsystems are stand-alone devices with internal RAID storage, eliminating need for additional servers, controllers, separate enclosures etc. The Vess A6000 Series uses a thoroughly tested and proven RAID engine for maximum reliability, all drive bays are hot-swappable, and models are available with redundant power supplies to ensure data safety and uninterrupted operation.

The Vess A6000 models include PCIe slots for added flexibility. The PCIe slots are suitable for video graphics cards, video encode/decode cards, RAID cards, or other useful functions available on the PCIe platform. Storage capacity can be scaled up by adding JBODs. Up to five JBODs can be added.

# **S**PECIFICATIONS

Model	Vess A6600	Vess A6800		
	General			
Form Factor	3U, 19" rack mount	4U, 19" rack mount		
Function	Storage Appliance for Video Surveillance	e		
Drives	Sixteen Hot-swappable drives 3.5" HDD (12Gbs SAS / 6Gbs SATA) 2.5" SSD	Twenty-four Hot-swappable drives 3.5" HDD (12Gbs SAS / 6Gbs SATA) 2.5" SSD		
Controller	Single			
Network	Two Gigabit Ethernet RJ-45 ports (1000	Base-T)		
System Processor	VA6600: Intel® Core™ i3-7101E / Intel Xeon E3-1275v5 VA6800: Intel® Core™ i7-7700			
System Memory	Default 8GB (Maximum 64 GB) @ DDR4 Non-ECC			
Internal Built-in Storage	128GB M.2			
Number of HDD Supported	SAS and iSCSI with 5 JBODs (144 through SAS 4U24 JBOD per system in terms of 4U24 Head)			
USB Ports	Front: two USB 2.0 / Rear: four USB 2.0, two USB 3.0			
Expansion Slot	PCle 3.0 x 16 PCle 3.0 x 8 PCle 3.0 x 4 PCle 3.0 x 1 M.2	<ul> <li>- 1 slot (PCIE4/6: x0/x16, x8/x8)</li> <li>- 1 slot (PCIE4: x8/x0)</li> <li>- 1 slot (PCIE7: shared with M.2)</li> <li>- 1 slot (PCIE5)</li> <li>- 1 slot</li> </ul>		
I/O Port	PS/2 x 1 D-Sub DVI Port x 1 HDMI Port x 1			
Audio	5 + 1 jack			

Model	Vess A6600	Vess A6800		
RAID				
RAID Levels Supported	0, 1, 1E, 3, 5, 6, 10 (0+1), 30, 50, 60			
Hot Spares	Multiple global or dedicated hot-spare d	rives with revertible option		
Maximum LUNs per System/Array	256/32			
	Software			
Supported OS (64-bit)	Windows 10 in default. Windows Server 2016R2			
Management	Graphical UI/SNMP via Ethernet, CLI via Ethernet, OPAS Service via USB, SDK or API for Integration			
Event Notification	Email, SNMP, Buzzer, LEDs			
System				
AC Input	100 ~ 240 VAC, 60 ~ 50Hz			
Current (Maximum)	8-4A ( 550W, 8A/100V, 4A/240V)			
Power Supply	550W (1+1@550W) in default. 1100W (2+1@550W) optional 1100W (2+1@550W) in default.			
Fan	Non-swappable			
Temperature	5° ~ 40°C (-40° ~ 60°C non-operational)			
Relative Humidity	Operational: 10% to 80% (Non-Condensing) Non-Operational: 10% to 95% (Non-Condensing)			
Dimensions (H x W x D)	131 x 503 x 447 mm       173 x 503 x 447 mm         (5.1 x 19.8 x 17.6 in)       (6.8 x 19.8 x 17.6 in)			
Safety/EMI	CE, FCC, VCCI, RCM, BSMI, KC, (EMI Class A), CB3, cTUVus4			
Warranty	3 years limited warranty			

# HARDWARE

The following section provides a summary of the front and back panel hardware features of Vess A6600, and Vess A6800 Storage Appliance for Video Surveillance. These enclosures are referred to collectively as Vess A6000 enclosures, Vess A6000 units or Vess A6000 subsystems throughout this document when the content applies to all models in the Promise Vess A6000 Series.

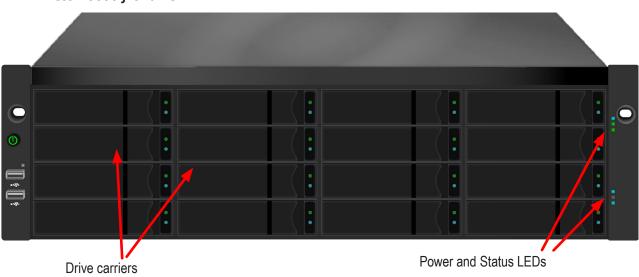
# FRONT PANEL HARDWARE

The front panel of Vess A6000 enclosures provide access to drives carriers. Vess A6000 units are shipped with secure covers to protect the drive carriers from being unintentionally removed.

For all Vess A6000 enclosures, defective drives can be replaced without interruption of data availability to the host computer. If so configured, a hot spare drive will automatically replace a failed drive, securing the fault-tolerant integrity of the logical drive. The self-contained hardware-based RAID logical drive in the Vess A6000 provides maximum performance in a compact external enclosure.

## FRONT OF VESS A6600

The Vess A6600 enclosure features handles on each side used to secure the enclosure to an equipment rack. The system power button and two USB ports are located on the left side, and most of the front LED indicators are located on the right side.



#### Vess A6600 front view

#### Vess A6800 front view

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# **S**ECURE COVER

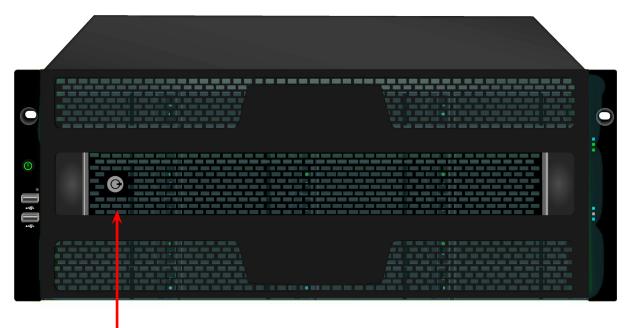
The Vess A6600/A6800/A6600/A6800 include secure covers to for better physical security and to help prevent unintended or accidental removal of hard drives. The cover are secured with a single tubular cam lock located near the left side of the cover. Turn the key clockwise to lock, counter clockwise to unlock.

#### Vess A6600 with secure cover (unlocked)



Tubular cam lock

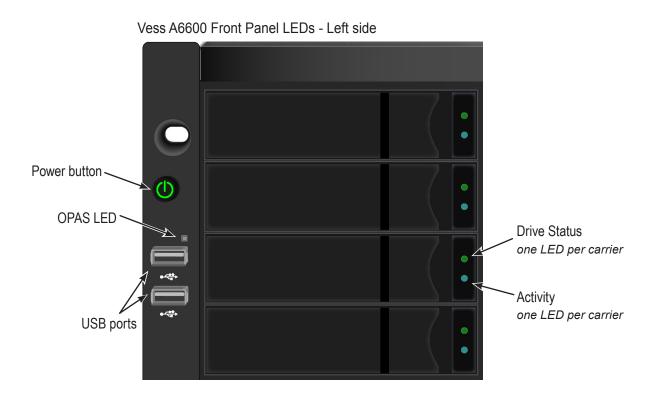
#### Vess A6800 with secure cover (locked)



Tubular cam lock

# FRONT PANEL LEDS

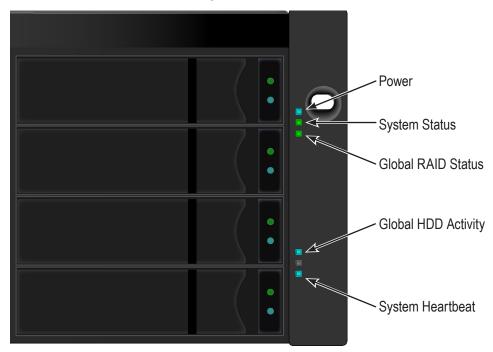
Descriptions of the LED behavior and function for Vess A6000 enclosures.



Left side LED behavior for the Vess A6000

LED	Description						
OPAS USB	<b>B</b> Lights GREEN if an OPAS device (USB disk) is detected, RED if the OPAS operation has failed, blinks GREEN when an OPAS operation is in progress.						
Drive Carrier LEDs (located on all drive carriers)							
Drive Status	Each drive carrier has two LEDs on the right side of the front, the Drive Status LED lo- cated above the Activity LED. The Drive Status LED displays GREEN when a drive is configured and working properly. When the lights are RED the HDD requires manual replacement. ORANGE indicates background RAID activity on this particular HDD, no user action is required.						
Drive Activity	Steady BLUE when HDD link is established, flashes BLUE during drive activity.						

Vess A6600 Front Panel LEDs - Right side



Right side LED behavior for the Vess A6000.

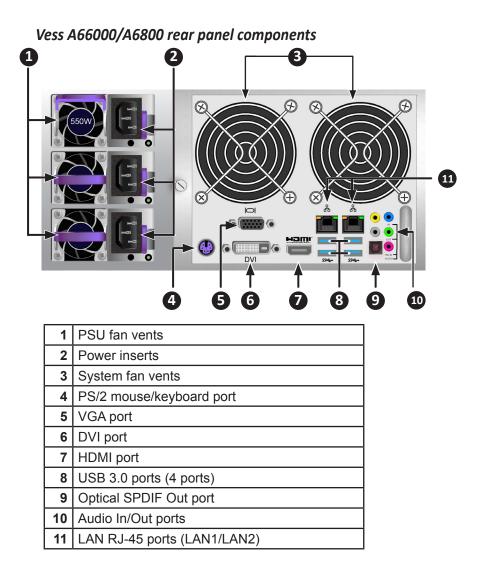
LED	Description
Power	Lights BLUE to indicate the system is powered on. Blinks BLUE in shutdown mode.
System Status	Lights GREEN when healthy, RED if there is a critical problem (LD offline, fan mal- function, voltage out of range, system temperature alert), blinks RED for HDD high temperature alert remains dark when not ready.
Global RAID Status	Lights GREEN when healthy or RED if any RAID volume is offline, ORANGE for critical state of any logical drive.
Global HDD Activity	Blinks BLUE to indicate one or more drives are being accessed, remains dark when no drives are being accessed.
System Heartbeat	Flashes BLUE slowly at regular intervals to indicate the firmware and software are operating normally.

# **R**EAR **P**ANEL HARDWARE

The rear panel of the Vess A6000 enclosures provide access to the hot-swappable power supplies, local management connection (via USB keyboard and VGA or HDMI monitor port), iSCSI (Ethernet) data ports, some units also provide I/O connections for audio sensor and alarm systems. The back panel includes two system fans.

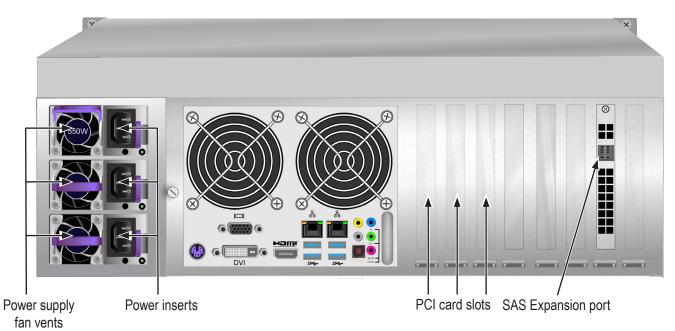
## Vess A6000 Rear Panel Components

The Vess A6600 enclosure features two hot-swappable power supplies (PSU). The Vess A6800 enclosure has three hot-swappable power supplies.

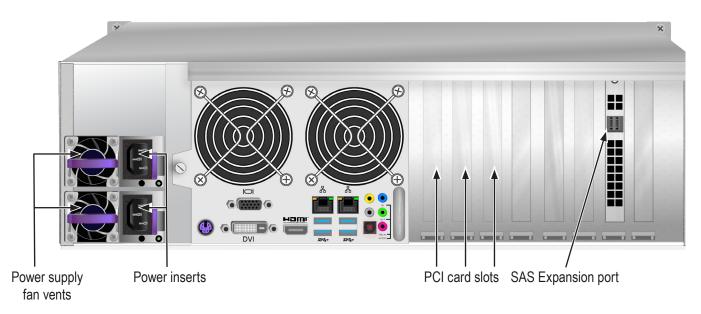


The rear panel of the Vess A6800 is nearly identical to the Vess A6600, except it is taller and has three power supplies. The form factor of the Vess A6800 is 4U, the Vess A6600 form factor is 3U.

#### Vess A6800 rear view



#### Vess A6600 rear view



## Vess A6000 Rear panel LED indicators

The LEDs on the rear panel include LEDs for Ethernet data ports and an LED for each of the hot-swappable

PSUs.

LED	Description
Link/Act and	The LED located above each port, on the left side, lights ORANGE when connected, flashes ORANGE when there is activity on the port and remains dark no connection has been established. The LED above and on the right of each port indicates connection speed, ORANGE is 100 Mbps, GREEN is 1000 Mbps, dark is 10 Mbps.
PSU	Each power supply LED lights GREEN to indicate normal operation. A RED LED indicates a problem or unit failure.

#### Vess A6000 Rear panel connections

Access to physical data and management connections are located on the back panel of the Vess A6000

including the optional I/O connections for sensor and alarm systems.

Feature	Description
D-sub VGA	This is also used for a video out connection for VGA monitors, it is also used to view the management interface.
Display Port	This is also used for a video out connection for Display Port monitors, it is also used to view the management interface.
DVI	This is also used for a video out connection for DVI monitors, it is also used to view the management interface.
HDMI	Provides video out connection for HDMI enabled monitors used to view the management interface.
USB	Use to connect to a USB keyboard for managing the Vess A6000 Series, or use it to trans- fer data to or from a USB memory device. There are four USB 2.0 ports and two USB 3.0 ports.
Audio In	Use for input from a peripheral audio device, such as a microphone. Plug-In Power microphones are supported.
Audio Out	Use for output (line out) peripheral audio device (speakers, for example).
Audio Mic	Use for microphone.

# HARDWARE SETUP

This chapter presents the basics on unpacking, setting up hardware for the Vess A6000. Hardware installation includes installing the unit in an equipment rack, connecting the power, making network, data and management connection to the device, and installing hard drives.

The sections in Hardware Setup include the following:

- "Unpacking"
- "Mounting the Vess A6000 in a rack"
- "Installing Disk Drives"
  - "Number of Drives Required"
  - "Installing or removing the security cover"
  - "Drive Slot Numbering"
  - "Vess A6000 drive carriers"
- "Management Path Connection"
- "Connect the Power"
- "Power On Enclosure"

# UNPACKING

Note

The Vess A6000 Series can accommodate SATA (6Gbps) or SAS (12Gbps/6Gbps) hard drives.

## PACKING LIST

The Vess A6000 box contains the following items:

- One of the following storage appliances:
  - Vess A6600 16-bay
  - Vess A6800 24-bay
- Screws for disk drives
- Three 1.5m (4.9 ft) power cords
- Sliding rail assembly for rack mounting (optional)
- Front panel bezel cover

# **MOUNTING THE ENCLOSURE IN A RACK**

The instructions here apply to 3U 16-bay Vess A6600, as well as the 4U 24-bay Vess A6800. The sliding rail rack mounting hardware is the same for both form factors.

### Cautions

• Do not populate any unit with hard drives until it has been securely installed in the rack.



- At least two persons are required to safely lift, place, and attach the Vess A6000 unit into a rack system.
- Do not lift or move the Vess A6000 unit by the handles, power supplies or the controller units. Hold the system itself.
- Do not install the Vess A6000 unit into a rack without rails to support the system.
- Only a qualified technician who is familiar with the installation procedure should mount and install the Vess A6000 unit.
- Mount the rails to the rack using the appropriate screws and flange nuts, fully tightened, at each end of the rail.
- Do not load the rails unless they are installed with screws as instructed.
- The rails available for the Promise Vess A6000 unit are designed to safely support that Promise Vess A6000 unit when properly installed. Additional loading on the rails is at the customer's risk.
- Promise Technology, Inc. cannot guarantee that the mounting rails will support your Promise Vess A6000 unit unless you install them as instructed.



#### Note

To lighten the Vess A6000 enclosure, you can remove the power supplies. Replace the power supplies after the Vess A6000 unit is mounted in your rack.

# MOUNTING ENCLOSURE IN A RACK

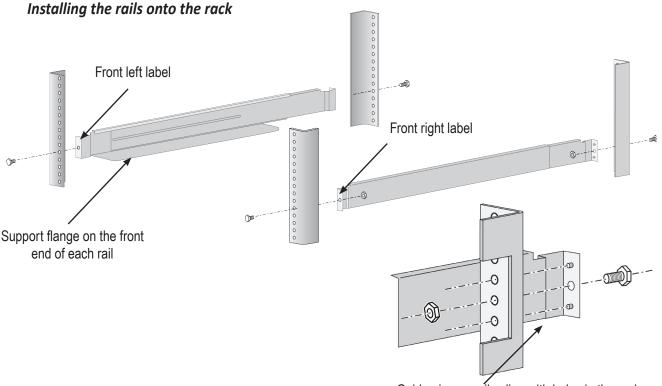


#### Note

Please refer to the Quick Installation Guide included with the mounting rails for more detailed rack installation instructions.

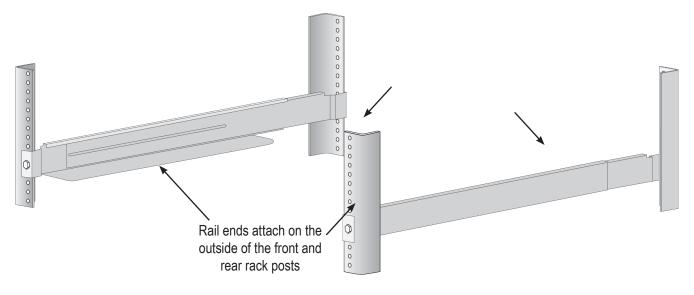
To install the Vess A6000 into a rack with the supplied mounting rails:

- 1. Check the fit of the mounting rails in your rack system.
- 2. Adjust the length of the mounting rails as needed.
  - The rear rail slides inside the front rail. The rail halves are riveted together and use no adjustment screws.
  - The front-left and front-right mounting rail ends are labeled.
  - · Be sure the front rail support is on the bottom facing inward
  - All rail ends, front and rear, attach at the outside of the rack posts.
  - The guide pins at the rail ends align with the holes in the rack posts.
  - Use the attaching screws and flange nuts from your rack system. Tighten the screws and nuts according to instructions for your rack system.

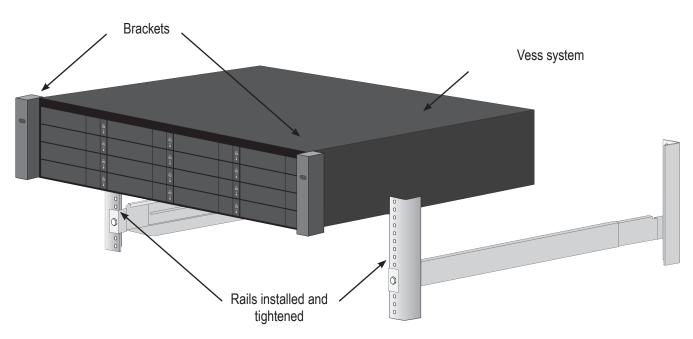


Guide pins on rails align with holes in the rack post

Rail ends attach to the outside of each post

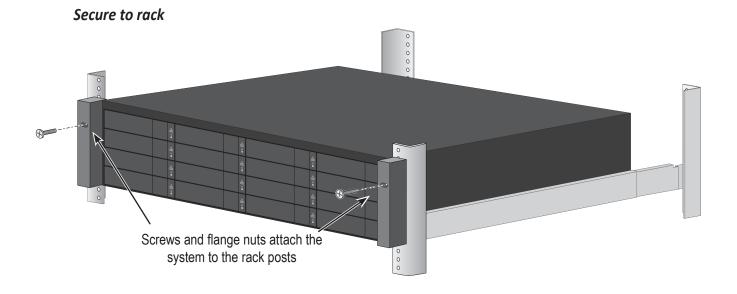


- 3. Place the Vess A6000 onto the rails.
  - At least two persons are required to safely lift the system.
  - Lift the Vess A6000 itself. Do not lift the system by its brackets.

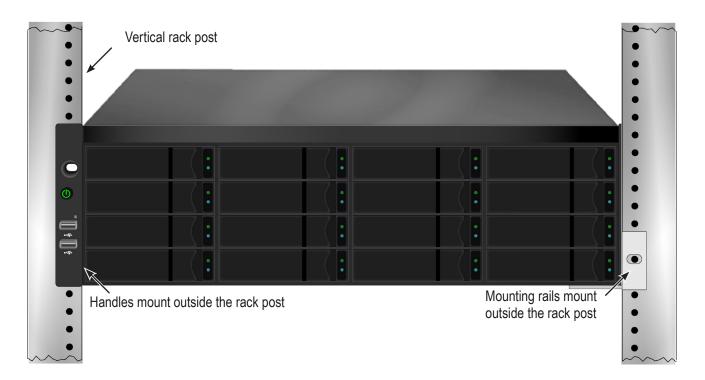


#### Placing the system onto the rack rails

- 4. Secure the enclosure to the rack.
  - The unit attaches to the rack posts using the included screws and flange nuts. One screw each side, in the upper hole only.
  - Use the attaching screws and flange nuts that came with the Vess A6000.



#### System installed in rack



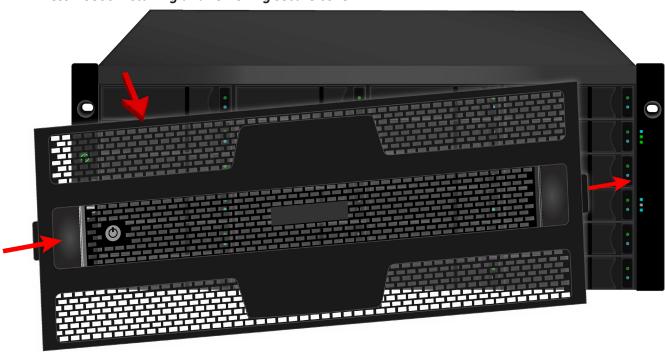
## **INSTALLING OR REMOVING THE SECURITY COVER**

The secure cover hardware is operated in the same fashion on the Vess A6000 models.

To attach the secure cover:

- 1. Make sure the lock is in the unlocked position. *To unlock, insert the key into the lock and turn counter clockwise*.
- 2. Insert the tab on the right side of the cover into the slot receptacle on the right handle.
- 3. Place the cover in position and push in the latch release (to the left of the keyhole).
- 4. Push the cover into position so that the tab on the right side inserts into the receptacle on the right handle when releasing the latch.
- 5. Insert the key and turn clockwise to lock.

To remove the cover, unlock it, press the latch release on the left side and pull the left end out first, holding it with both hands.



#### Vess A6800 installing and removing secure cover

# INSTALLING DISK DRIVES

The Vess A6000 subsystems support:

- SATA / SAS hard disks
- 3.5-inch hard disk drives
- SAS 2.5-inch hard disk drives (Optional)

# NUMBER OF DRIVES REQUIRED

The table below shows the number of drives required for each RAID level

Level	Number of Drives	Level	Number of Drives
RAID 0	1 or more	RAID 6	4 to 32
RAID 1	2 only	RAID 10	4 or more*
RAID 1E	2 or more	RAID 50	6 or more
RAID 5	3 to 32	RAID 60	8 or more

\*Must be an even number of drives.



#### Caution

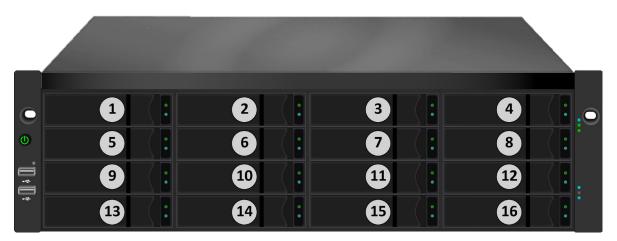
The Vess A6000 supports disk drive hot-swapping. To avoid hand contact with an electrical hazard, do not remove more than one drive carrier a time.

### **D**RIVE **S**LOT **N**UMBERING

You can install any suitable disk drive into any slot in the enclosure. The diagram below shows how drive slots are numbered on the Vess A6600.

Slot numbering is reflected in the web management user interfaces.

Drive slot numbering for Vess A6600



Drive slot numbering for Vess A6800

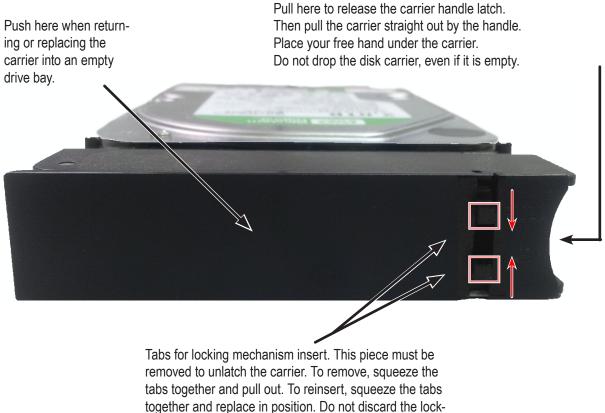
0	1		2		3		4	
	5	•	6	•	7	•	8	
Ċ	9		10	•	11		12	
¢ U ¢	13		14	•	15		16	
	17		18	•	19		20	•
	21		22		23		24	•

Install all of the drive carriers into the enclosure to ensure proper airflow, even if you do not populate all the carriers with disk drives.

## **R**EMOVING THE **D**RIVE **C**ARRIER

The drive carrier accommodates 2.5-inch and 3.5-inch drives.

#### Vess A6600/A6800 Disk carrier with HDD installed - front view



ing mechanisms.



### Cautions

Swing open the drive carrier handle before you insert the drive carrier into the enclosure.

To avoid hand contact with an electrical hazard, remove only one drive carrier a time.

# INSTALLING 3.5" DISK DRIVE IN THE CARRIER

The instructions below apply 3.5" hard disk drives installed in drive carriers intended for use with models Vess

A6600 and Vess A6800.

- 1. Remove a disk drive carrier.
- 2. Carefully lay the disk drive into the drive carrier at the front, so that the screw holes on the sides line up correctly with the power and data connectors facing away from the carrier handle.
- 3. Insert the screws through the holes in the drive carrier and into the sides of the disk drive.

Install only the counter-sink screws supplied with the drive.

- Install four screws per drive.
- Snug each screw. Be careful not to over-tighten.
  - 4. Reinstall the drive carrier into the enclosure.

Repeat steps 1 through 3 until all of your disk drives are installed.

# Installing 2.5" Disk Drive in the Carrier

The instructions below apply 2.5" hard disk drives installed in drive carriers intended for use with models Vess A6600 and Vess A6800.

- 1. Remove a disk drive carrier.
- 2. Carefully lay the disk drive into the drive carrier at the front, so that the screw holes on the bottom of the carrier line up correctly with the power and data connectors facing away from the carrier handle.
- 3. Insert the screws through the holes on the bottom of the drive carrier and into the bottom of the disk drive.

Install only the counter-sink screws supplied with the drive.

- Install four screws per drive.
- Snug each screw. Be careful not to over-tighten.
  - 4. Reinstall the drive carrier into the enclosure.

Repeat steps 1 through 3 until all of your disk drives are installed.

# **MANAGEMENT PATH CONNECTION**

This section describes how to establish a management connection the Vess A6000 subsystems. Management through the Gigabit network connection is done using Promise Management GUI, a web browser based GUI.

#### NETWORK CONNECTION

Vess A6000 have two Gigabit Ethernet RJ-45 ports on the rear panel for connection to an Ethernet network. Use this connection with Promise Management GUI to login as the device administrator.

To establish the management path:

- Attach one end of an Ethernet cable to the network connector or standard NIC in the Host PC.
   Attach the other end of the Ethernet cable to one of the ports on the standard network switch.
- Attach one end of an Ethernet cable to one of the ports on the standard network switch.
   Attach the other end of the Ethernet cable to either 1GbE network port on the Vess A6000 system.
   (See illustration below for port location)

If you have multiple Vess A6000 systems, Host PCs or Servers, repeat steps 1 and 2 as required.

3. Follow the instructions for managing the basic settings of the Vess A6000.

# **CONNECT THE POWER**

Insert one power cable into the power receptacle for each power supply and connect the each PSU to a suitable

power source. The subsystem is equipped with three power supplies in an N+1 arrangement.

Each PSU has a Status LED. After boot up, check the LEDs on each power supply on the back of the device.

These LEDs will light green to indicate normal operation. A red LED indicates a problem or unit failure.

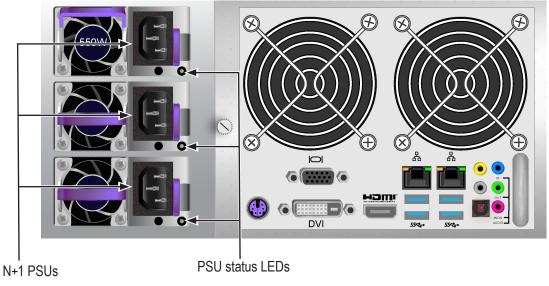


#### Important

The Vess A6800 features three N+1 power supplies. In this arrangement, one PSU is redundant, so a minimum of two PSUs are needed to power up the enclosure.

The Vess A6600 feature two N+1 power supplies. In this arrangement, one PSU is redundant, so a minimum of one PSU is needed to power up the enclosure.

#### Vess A6800 N+1 power connections



Connect all power supplies to a suitable power source.



# Warning

Turn off the power and disconnect all power cord before servicing the Vess A6600 and Vess A6800.

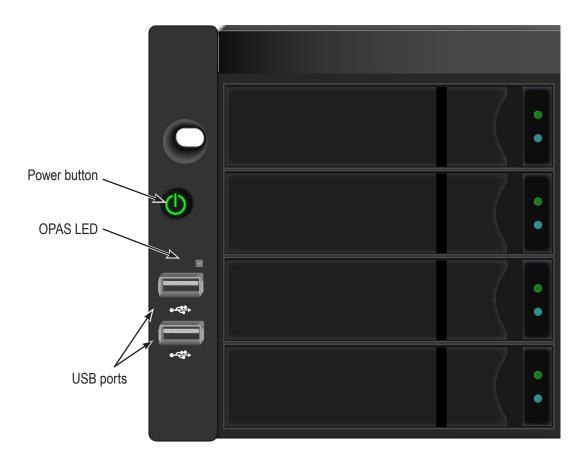
# **POWER ON ENCLOSURE**

With the power supplies connected, the system can now be powered on.

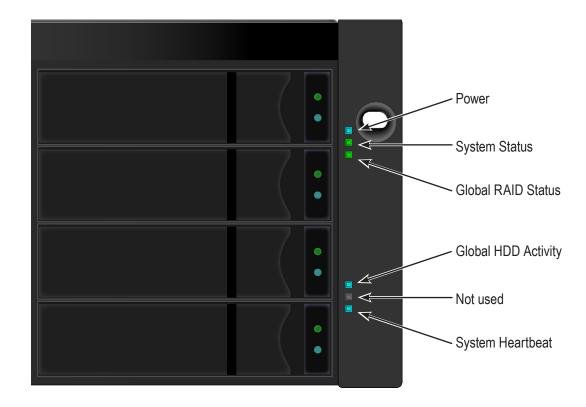
#### If you are using JBOD storage expansion setup, power on the JBODs first.

To power on the Vess A6000 subsystem, press the Power button on the front left bracket facing (see figure below). Observe the LEDs on the front panel to make certain the boot up proceeds smoothly.

## Vess A6600 front panel components, left side



## Vess A6600 front right side



## FRONT PANEL LED BEHAVIOR

The table below describes LED behavior when boot-up is finished and the system is functioning normally:

LED	Description
Power	Lights BLUE to indicate the system is powered on.
System Status	Lights GREEN when healthy, RED if there is a critical problem (LD offline, fan malfunction, voltage out of range, system temperature alert), blinks RED for HDD high temperature alert remains dark when not ready.
Global RAID Status	Lights GREEN when healthy or RED if any RAID volume is offline, ORANGE for critical state of any logical drive, or when the system is rebuilding.
Global HDD Activity	Blinks BLUE to indicate one or more drives are being accessed, lights steady BLUE when no drives are being accessed.
System Heartbeat	Blinks BLUE slowly at regular intervals to indicate the firmware and software are operating normally.
OPAS USB	Lights GREEN if an OPAS device (USB disk) is detected, remains dark if the OPAS operation has failed, blinks GREEN when an OPAS operation is in progress.

# CONNECT TO ISCSI STORAGE AREA NETWORK (SAN)



#### Important

For a list of supported HBA NICs and switches, download the latest compatibility list from PROMISE support: http://www.promise.com/support/.

This arrangement requires:

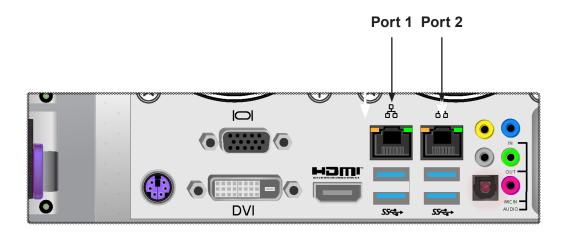
- An iSCSI HBA network interface card (NIC) in the host PC or server
- A GbE network switch
- A standard network switch



Note

Only one iSCSI data cable is required between each Vess enclosure and the GbE network switch. However, you can attach multiple cables to create redundant data paths.

#### Gigabit Ethernet Network ports on rear panel



# **PROMISE MANAGEMENT GUI**

This chapter describes using Promise Management GUI to monitor and manage your RAID system.

# LOGGING INTO PROMISE MANAGEMENT GUI

You can log into Promise Management GUI in either of two ways:

- "Logging in at the Enclosure" on page 29
- "Logging in over the Network" on page 30

## LOGGING IN AT THE ENCLOSURE

At the Vess A6000 enclosure to log into Promise Management GUI, do one of the following actions:

- Double-click the Promise Management GUI desktop icon.
- Choose Promise Management GUI in the Windows Programs menu.
- Follow the steps under "Logging in over the Network" on page 30.



#### Note

The default IP settings for the Gigabit Ethernet ports are: Port 1 = 192.168.0.1 Port 2 = 192.168.1.1

IP settings for the ports are controlled by the OS. Use the normal IP settings configuration procedure for the OS you are using if you want to change the default settings.

## Logging in over the Network



#### Important

For Vess A6000 Series running Windows OS, it is necessary to disable the Windows Firewall in order to allow access to Promise Management GUI through the network interface. If the Firewall is running, no management access is permitted from the network.

You can log into Promise Management GUI from any PC with a network connection to the and Vess A6000 Series enclosure.

- 1. Launch your Browser.
- 2. In the Browser address field, type the information provided below. Then press Enter. Note that this

example uses the default IP address for Port 1

If you chose External SSL Security during installation, use the Secure Connection. Otherwise, use the Regular

Connection.

#### **Regular Connection**

- Promise Management GUI uses an HTTP connection......http://

Together, your entry looks like this:

http://192.168.0.1:8090

#### Secure Connection

- Enter the Subsystem IP address ...... (Port 1 = 192.168.0.1 / Port 2 = 192.168.1.1)

Together, your entry looks like this:

https://192.168.0.1:443/



## Note

•

- You can enter the Host PC's network name in place of the IP address.
- If you are logging in at the Host PC, you can enter local Host in place of the IP address.
- Whether you select a regular or a secure connection, your login to Promise Management GUI and your user password are always secure.

# LOGIN SCREEN

When the opening screen appears:

- 1. Type administrator in the User Name field.
- 2. Type **password** in the Password field.
- 3. Click the **Login** button.

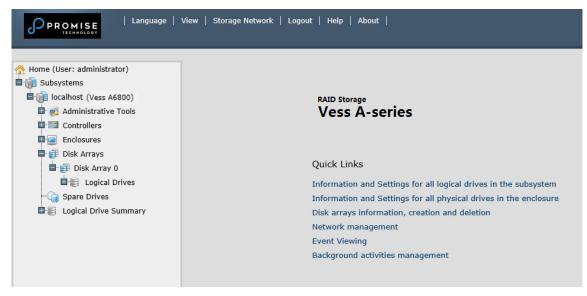
The User Name and Password are case sensitive.

#### The Promise Management GUI login screen

PROMISE	Language	
		Luser Name
		Password Login
		Logout Successful.

After logging in, the Quick Links menu appears.

#### **Quick Links menu**



# Using the Promise Management GUI Interface

Promise Management GUI is browser-based RAID management software with a graphic user interface. Basic user interface components and functions include:

Language   View   Storage Network   Logout   Help   About						
Home (User: administrator) Subsystems Controllers Controllers Disk Arrays Logical Drive Summ.	Background Activities         Information       Settings       Event       ▼       Background         ▼       Background Activities       ▼       Background activity is running.         ▼       Background Activity Parameters       ▼       Background Activity Parameters         Rebuild Rate       Background Synchronization Rate       ■         Logical Drive Initialization Rate       ■       ■         Redundancy Check Rate       ™       ™         Migration Rate       ■       ■         PDM Rate       ■       ■         Transition Rate       ■       ■         Reassigned Block Threshold       ■       ■         Error Block Threshold       ■       ■         Auto Rebuild       ■       ■         Last Media Patrol Start Time       ■       ■         Last Media Patrol Stop Time       ■       ■	Activities Scheduler Lock				

Promise Management GUI interface - Subsystem home page

There are three parts to the Promise Management GUI interface:

- 1. Header
- 2. Tree View
- 3. Event Frame

## Using the Header

The Header contains the following items:

Language – Choose a display language

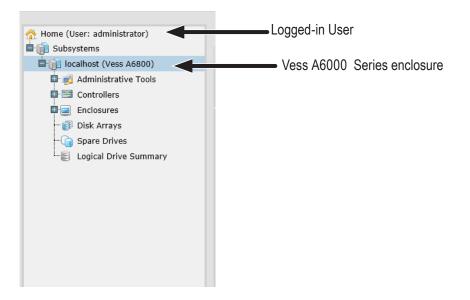
**View** – To view the Event Frame,

Logout – To logout

## Using Tree View

Tree View enables you to navigate around all components of the Vess A6000 enclosure, software management, RAID controller, enclosure, physical drives, disk arrays, logical drives, and spare drives. The figure below shows the components of Tree View.

#### Promise Management GUI Tree View



The Administrative Tools section is different for the Administrator and Super Users than for other users. The remainder of the Tree is the same for all users.

# Using Management View

Management View displays information and settings menus according to the item you choose in Tree View. It presents the user interface for the Vess A6000 enclosure, including creation, maintenance, deletion, and monitoring of disk arrays and logical drives. Function tabs access menus to control specific actions and processes.

Click the **Help** link to the right of the tabs in Management View to access online help for the function currently displayed.

# CHOOSING A DISPLAY LANGUAGE

Promise Management GUI displays in the following languages:

- English
   French
- Simplified Chinese
- Traditional Chinese
  - Japanese Spanish
- Korean
- Arabic

.

Turkish

German

Italian

Portuguese

Polish

Russian

To change the display language:

- 1. Click the Language drop-down menu in the Header.
- 2. Highlight the language you prefer.

Promise Management GUI displays in the chosen language.

# VIEWING THE EVENT FRAME

To view the Event Frame, click Show Event Frame in the Header. To hide the Event Frame, click Hide Event

Frame in the Header.

In the event frame, events are listed and sorted by:

- **Device** Disk array, logical drive, physical drive, controller, etc.
- Event ID The hexadecimal number that identifies the specific type of event
- Severity See below:
  - Information Information only, no action is required
  - Warning User can decide whether or not action is required
  - Minor Action is needed but the condition is not serious at this time
  - Major Action is needed now
  - Critical Action is needed now and the implications of the condition are serious
  - Fatal Non-Recoverable error or failure has occurred
- Time Time and date of the occurrence
- **Description** A brief description of the event

You can also view events by clicking the Subsystems icon in Tree View, then clicking the Event tab in Management View.

# Logging out of Promise Management GUI

There are two ways to log out of Promise Management GUI:

- Close your browser window
- Click Logout in the Promise Management GUI Header

Clicking **Logout** brings you back to the Login Screen. After logging out, you must enter your user name and password in order to log in again.

# **SUBSYSTEM MANAGEMENT**

The menus listed under Subsystems are all the menus used for device management. Click on the Subsystems icon to view read-only information for the Vess A6000 including the management IP address, Alias, Model and WWN.

To view the menus used for system management, click the + symbol of the Subsystems icon to reveal the child menu icons for the following:

- Administrative Tools (includes links for User Management, View Network Settings, Performance Monitoring and Software Management)
- **Controllers** (view controller information and manage settings) •
- Enclosures (view device information and virtual enclosure, set temperature thresholds for warnings and enable/disable warning buzzer)
- **Disk Arrays** (manage disk arrays)
- **Spare Drives** (manage spare drives)
- Logical Drives Summary (read-only logical drive information display)

Click on the subsystem IP address and model name listed under the Subsystems top-level menu icon in Tree View. In the Information tab, the following information for the subsystem appears:

- Alias Vendor
- Model Serial Number
- World Wide Number Part Number
- Revision Number System Date & Time •

Here you can also save a System Service Report (useful for troubleshooting) in the form of an HTML file to the computer you are using by clicking on the **Save** button. See "Saving a Service Report".

The Subsystem home menu includes the following function tabs:

- Information (described above)
- **Settings** (assign an Alias)

- **Background Activities**
- **Event** (list runtime and NVRAM events)
- Lock (lock/unlock subsystem) •

Scheduler (schedule background activities)

# **BACKGROUND ACTIVITIES**

Background activities perform a variety of preventive and remedial functions on your physical drives, disk arrays, logical drives, and other components.

You can run a background activity immediately or schedule it to run at a later time.

Setting options for each activity are listed after the scheduling options. These settings determine how the background activity affects I/O performance.

## VIEW CURRENT BACKGROUND ACTIVITIES

To view current background activities:

- 1. Click the Subsystem icon of the subsystem on which you want to view Background Activities.
- 2. In the Subsystem menu, click the Background Activities tab. Background Activities currently running are displayed in the top portion of the menu. You can also view the current Background Activities parameter settings in the lower part of the menu. Click the Background Activity Parameters menu expander to view the current parameter settings.

## View Background Activities Parameters settings

To view current background parameter settings:

- 1. Click the Subsystem icon of the subsystem on which you want to view Background Activities.
- 2. Click the Background Activity Parameters menu expander to view the current parameter settings. The parameters listed are as follows:
  - Rebuild Rate
  - Background Synchronization Rate
  - Logical Drive Initialization Rate
  - Redundancy Check Rate
  - Migration Rate

- Transition Rate
- Reassigned Block Threshold
- Error Block Threshold
- Enable Media Patrol
- Enable Auto Rebuild

# MANAGE BACKGROUND ACTIVITIES SETTINGS

The parameters listed in the Background Activities menu are configured in the Background Activities Settings

menu. To change Background Activities settings

- 1. Click the Subsystem icon of the subsystem on which you want to view Background Activities.
- 2. Click the menu expander between the Background Activities tab and the Scheduler tab and select the

Settings option. The following settings can be configured:

- Rebuild Rate High, Medium, Low
- Background Synchronization Rate High, Medium, Low
- Logical Drive Initialization Rate High, Medium, Low
- Redundancy Check Rate High, Medium, Low
- Migration Rate *High, Medium, Low*
- PDM Rate *High, Medium, Low*
- Transition Rate *High, Medium, Low*
- Reassigned Block Threshold
- Error Block Threshold
- Enable Media Patrol
- Enable Auto Rebuild

These settings can be also scheduled using the Scheduler. See the instructions for using schedules following the parameters descriptions below.

# **R**EBUILD **S**ETTINGS

To change Rebuild setting the in Background Activities Settings menu:

- 1. Use the **Rebuild Rate** drop-down menu to choose a rate:
  - Low Fewer system resources to the Rebuild, more to data read/write operations.
  - **Medium** Balances system resources between the Rebuild and data read/write operations.
  - High More system resources to the Rebuild, fewer to data read/write operations.
- 2. To enable Auto Rebuild (rebuilds when you swap out the failed drive with a new one) Check the **Enable**

#### Auto Rebuild box.

3. Click the **Submit** button.

#### Rebuild Rate

When you rebuild a disk array, you are actually rebuilding the data on one physical drive.

- When a physical drive in a disk array fails and a spare drive of adequate capacity is available, the disk array begins to rebuild automatically using the spare drive.
- If there is no spare drive of adequate capacity, but the Auto Rebuild function is ENABLED, the disk array begins to rebuild automatically as soon as you remove the failed physical drive and install an unconfigured physical drive in the same slot.
- If there is no spare drive of adequate capacity and the Auto Rebuild function is DISABLED, you must replace the failed drive with an unconfigured physical drive, then perform a **Manual Rebuild**.

# **BACKGROUND SYNCHRONIZATION**

Synchronization is automatically applied to redundant logical drives when they are created. Synchronization recalculates the redundancy data to ensure that the working data on the physical drives is properly in sync.

#### Background Synchronization Rate

1. To change Background Synchronization Rate setting the in Background Activities Settings menu: Click the

Synchronization Rate drop-down menu and choose a rate:

- **Low** Fewer system resources to Synchronization, more to data read/write operations.
- **Medium** Balances system resources between Synchronization and data read/write operations.
- **High** More system resources to Synchronization, fewer to data read/write operations.
- 2. Click the **Submit** button.

## LOGICAL DRIVE INITIALIZATION

Technically speaking, **Initialization** is a foreground activity, as you cannot access a logical drive while it is initiating.

Initialization is normally done to logical drives after they are created from a disk array. Initialization sets all data bits in the logical drive to zero. The action is useful because there may be residual data on the logical drives left behind from earlier configurations. For this reason, Initialization is recommended whenever you create a logical drive.

#### Logical Drive Initialization Rate

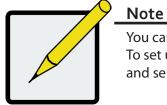
To change Logical Drive Initialization Rate setting the in Background Activities Settings menu:

- 1. Click the Logical Drive Initialization Rate drop-down menu and choose a rate:
  - Low Fewer system resources to Initialization, more to data read/write operations.
  - **Medium** Balances system resources between Initialization and data read/write operations.
  - **High** More system resources to Initialization, fewer to data read/write operations.
- 2. Click the **Submit** button.

# **R**EDUNDANCY **C**HECK

Redundancy Check is a routine maintenance procedure for fault-tolerant disk arrays (those with redundancy)

that ensures all the data matches exactly. Redundancy Check can also correct inconsistencies.



You can use the scheduler to set up a Redundancy Check Schedule. To set up a schedule, click the menu expander to the right of the **Scheduler** tab and select *Redundancy Check Schedule*.

## Redundancy Check Rate

To change Redundancy Check Rate setting the in Background Activities Settings menu:

- 1. Click the Redundancy Check Rate drop-down menu and choose a rate:
  - **Low** Fewer system resources to Redundancy Check, more to data read/write operations.
  - **Medium** Balances system resources between Redundancy Check and data read/write operations.
  - **High** More system resources to Redundancy Check, fewer to data read/write operations.
- 2. Click the **Submit** button.

# PDM

Predictive Data Migration (PDM) is the migration of data from the suspect physical drive to a spare drive, similar to rebuilding a logical drive. But unlike Rebuilding, PDM constantly monitors your physical drives and automatically copies your data to a spare drive before the physical drive fails and your logical drive goes Critical.

#### PDM Settings

To change PDM setting the in Background Activities Settings menu:

- 1. Click the PDM Rate drop-down menu and choose a rate:
  - Low Fewer system resources to PDM, more to data read/write operations.
  - **Medium** Balances system resources between PDM and data read/write operations.
  - High More system resources to PDM, fewer to data read/write operations.
- 2. Highlight the current values in the block threshold fields and input new values.

Reassigned Block Threshold range is 1 to 512 blocks.

Error Block Threshold range is 1 to 2048 blocks.

3. Click the **Submit** button.

## **T**RANSITION

Transition is the process of replacing a revertible spare drive that is currently part of a disk array with an unconfigured physical drive or a non-revertible spare drive.

#### Transition Rate

To change Transition Rate setting the in Background Activities Settings menu:

- 1. Click the Transition Rate drop-down menu and choose a rate:
  - Low Fewer system resources to Transition, more to data read/write operations.
  - **Medium** Balances system resources between Transition and data read/write operations.
  - **High** More system resources to Transition, fewer to data read/write operations.
- 2. Click the **Confirm** button.

# Media Patrol

Media Patrol is a routine maintenance procedure that checks the magnetic media on each disk drive. Media Patrol checks are enabled by default on all disk arrays and spare drives. Media Patrol is concerned with the media itself, not the data recorded on the media. If Media Patrol encounters a critical error, it triggers PDM if PDM is enabled on the disk array.

#### Media Patrol Settings

Media Patrol is enabled or disabled using the Background Activities menu or you can create a schedule to run

Media Patrol.

- To enable Media Patrol, click on the Subsystem in Tree View then click on the Background Activities menu tab. Click to check the *Enable Media Patrol* option. Notice also that the *Auto Rebuild* option is here as well. If you want to automatically begin rebuilding a logical drive as soon as a faulty drive is replaced, make sure this option is enabled.
- To begin Media Patrol manually, click on the menu expander to the right of the Background Activities tab and scroll down and select *Start Media Patrol* to see the Start Media Patrol menu. Then click on the **Start** button.
- To schedule Media Patrol, click on the menu expander to the right of the Scheduler tab and scroll down and select *Add Media Patrol Schedule* to open the schedule menu. Use this menu to add a Media Patrol schedule.

# **MANAGING ACTIVITY SCHEDULES**

Schedules for **Media Patrol**, **Redundancy Check** and **Spare Drive Check** can be created to run during off peak times.

## **A**DD OR DELETE AN ACTIVITY SCHEDULE

To add, enable or delete an activity schedule, click on the Subsystem in Tree View, then click on the Scheduler menu expander to the right of the Scheduler tab. Scroll down to the schedule option you want to view that menu. Schedule options are *Add Media Patrol Schedule*, *Add Redundancy Check Schedule*, *Add Spare Check Schedule* and *Delete Schedule*.

#### VIEW OR MODIFY AN EXISTING ACTIVITY SCHEDULE

To view existing schedules including the recurrence, start time and status of existing schedules, click on the Scheduler tab. Here you can then modify any listed schedule by clicking on the name of the schedule in the list.

# **EVENT LOGS**

Event logs are useful for troubleshooting, tracking functions and monitoring subsystems. To view, save or clear subsystem event logs, click on the subsystem in Tree View, then click on the Event menu expander. Choose to display *Runtime Events* or *NVRAM Events*. Event logs can be saved as a simple text file by clicking the **Save** button in either menu. To clear the log and start fresh, click the **Clear Event Log** button.

# **ADMINISTRATIVE TOOLS**

Click the + symbol of the Administrative Tools icon reveal subsystem administrative tools menu links for User Management, View Network Settings, Performance Monitoring and Software Management. The Administrative Tools menu lists text hyperlinks to these same menus, plus links to menus to Restore Factory Default settings, Clear Statistics and Save System Service Report.

# **R**ESTORE FACTORY DEFAULT SETTINGS

To restore any firmware or software settings to the default values:

- 1. Click on the Administrative Tools icon.
- 2. Click on the *Restore Factory Defaults* link to reveal a new menu.
- 3. Check mark the option boxes for the settings you want to return to the factory default values. Default

Settings options include: **Firmware Default Settings** 

Software Default Settings

- **Background Activities**
- **Controller Settings** •

•

**Enclosure Settings** •

Web Server Settings

Service Settings

Email Settings

- Physical Drive Settings •
- Subsystem Settings •
- 4. Click the Submit button to return the selected settings to default values. To deselect all options and start over, click the Reset button.

## **CLEAR STATISTICS**

To clear all subsystem statistics for controllers, ports physical drives and logical drives:

- Click on the Administrative Tools icon.
- 2. Click on the *Clear Statistics* link to reveal a new menu.
- 3. Click on the **Submit** button to clear all device statistics.

# User Management

User Management deals with user accounts.

# VIEWING USER INFORMATION

The view a list of users, their status, access privileges, display name, and email address:

- 1. Click the Administrative Tools icon.
- 2. Click the User Management icon.

The Information tab appears in Management View.

# MAKING USER SETTINGS

To change settings of other users:

- 1. Log into Promise Management GUI as the Administrator or a Super User.
- 2. Click the Administrative Tools icon.
- 3. Click the User Management icon.
- 4. Click the **Information** tab.
- 5. In the list of users, click the link of the user whose settings you want to change.

The Settings screen for the chosen user displays.

- 6. Enter or change the settings for this user.
  - Enable/disable this user
  - Display name
  - Privilege.
- 7. Click the **Submit** button.

The Administrator or Super User can change another user's password.

## MAKING YOUR OWN USER SETTINGS

To change your own user settings:

- 1. Log into Promise Management GUI under your own user name.
- 2. Click the Administrative Tools icon.
- 3. Click the User Management icon.
- 4. Click the **Settings** tab in Management View.
- 5. Enter or change the display name or mail address.
- 6. Click the **Submit** button.

# CHANGING YOUR OWN PASSWORD

To set or change your own password:

- 1. Log into Promise Management GUI under your own user name.
- 2. Click the Administrative Tools icon.
- 3. Click the User Management icon.
- 4. Click the **Password** tab in Management View.
- 5. Enter the current password in the Old Password field.
- 6. If you do not have a password, leave this field blank.
- 7. Enter the new password in the New Password field.
- 8. Enter the new password in the Retype Password field.
- 9. Click the **Submit** button.

# **CREATING A USER**

To create a user:

- 1. Log into Promise Management GUI as the Administrator or a Super User.
- 2. Click the Administrative Tools icon.
- 3. Click the User Management icon.
- 4. Click the **Create** tab in Management View.
- 5. Enter a user name in the User Name field.
- 6. Enter a password for this user in the New Password and Retype Password fields.
- A password is optional. If you do not assign password, tell this user to leave the password field blank when he/

she logs into to Promise Management GUI.

- 7. Check the *Enabled* box to enable this user on this subsystem.
- 8. Enter a display name in the Display Name field.

A display name is optional but recommended.

9. Choose a privilege level from the Privilege drop-down menu.

For definitions of each privilege level, see the List of User Privileges below.

10. Click the Submit button.

# LIST OF USER PRIVILEGES

- View Allows the user to see all status and settings but not to make any changes
- Maintenance Allows the user to perform maintenance tasks including
- Rebuilding, PDM, Media Patrol, and Redundancy Check.
- Power Allows the user to create (but not delete) disk arrays and logical drives, change RAID levels, change stripe size; change settings of components such as disk arrays, logical drives, physical drives, and the controller.
- Super Allows the user full access to all functions including create and delete users and changing the settings of other users, and delete disk arrays and logical drives. The default "administrator" account is a Super User.

## **D**ELETING A **U**SER

There is always at least one Super User account. You cannot delete the user account you used to log in. To delete a user:

- 1. Log into Promise Management GUI as the Administrator or a Super User.
- 2. Click the Administrative Tools icon.
- 3. Click the User Management icon.
- 4. Click the **Delete** tab in Management View.
- 5. Check the box to the left of the user you want to delete.
- 6. Click the **Submit** button.
- 7. Click **OK** in the confirmation box.

# VIEW NETWORK SETTINGS

To view network settings for the Ethernet ports, including the port used for access to Promise Management GUI, click on the View Network Settings icon under Administrative Tools. Information listed for each port includes:

- If the port is enabled/disabled
- If the link is up/down

- IP address
- Subnet mask

IP type IPv4/IPv6

- MAC address
- Maximum port speed

# Software Management

The Software Management menu is used to manage settings for Email, SNMP settings and Web services. The Email function is used for sending notifications of events. The Web service is used for remote network connection to the Promise Management GUI management interface. This is also where you can export and import configuration script files and user database files.

# IMPORTING A CONFIGURATION SCRIPT

You can import a previously saved configuration script to automatically configure your Vess A6000 subsystem. The script must be a plain, non-encrypted text file. This file can be saved from the same system, or from another Vess A6000 subsystem. See the next section, "Exporting a Configuration Script" on page 55 for instructions on how to save the file to your host PC.



## Cautions

Do NOT attempt to write or modify a configuration script until you receive guidance from Technical Support.

Importing a configuration script overwrites the current settings on your Vess A6000 subsystem.

To import a configuration script for automatic configuration of a subsystem:

- 1. Click the **Administrative Tools** icon.
- 2. Click the **Software Management** icon.
- 3. Click the **Import** tab in the Software Management menu.
- 4. Choose *Configuration Script* from the **Type** drop-down menu.
- 5. Click the **Import** button.
- 6. Click **Browse** and find the file "Configscript.txt" on the Host PC.
- 7. Click the **Submit** button.

The configuration script is loaded and applied automatically.

# **EXPORTING A CONFIGURATION SCRIPT**

You can save the configuration from one Vess A6000 subsystem, export it, and then import it to automatically configure your other Vess A6000 subsystems.

To export a configuration script:

- 1. Click the **Administrative Tools** icon.
- 2. Click the **Service Management** icon.
- 3. Click the **Export** tab in the Service Management menu.
- 4. Choose *Configuration Script* from the **Type** drop-down menu.
- 5. Click the **Export** button.
- 6. Select a location on the Host PC for the downloaded file and save the file.

The file is saved to your PC as "Configscript.txt".



# Cautions

Do NOT attempt to write or modify a configuration script until you receive guidance from Technical Support.

# SAVING A SERVICE REPORT

A Service Report is a detailed report covering the configuration and status of all components in your RAID system. A support technician or field engineer might request a service report for the purpose of diagnosis and troubleshooting.

To save a system configuration file:

- Click on the Subsystem icon (IP address and device name) in Tree View to open the Subsystem Information display.
- 2. Click the **Save** button in the Save System Service Report row of the information display.

Information for the report is gathered and compiled. This action takes up to a few minutes, depending on the size of your RAID system.

 Determine where you want to store the file on the Host PC, then click the Save button in the pop-up menu.

The report saves to your Host PC as a compressed HTML file.

- 4. Double-click the downloaded file to decompress it.
- 5. Double-click the report to open it in your default browser.

The Service Report includes the following topics:

- About Report utility
- BBM Info Bad Block Manager
- BGA Summary Status and settings
- Buzzer Info
- Controller Info
- Disk Array Info
- Disk Array Dump info
- Disk Array Verbose Info
- Enclosure Info
- Error Table Info
- Event Info NVRAM
- Event Info Runtime
- LogDrive Info Basic logical drive information
- LogDrive Dump Info Diagnostic information
- Logical Drive Verbose Info Full logical drive information

- Network Info Virtual port
- Phydriv Info Basic physical drive information
- Phydriv Verbose Info Full physical drive
- SWMGT Info Software management
- Service Setting Email
- Service Setting Webserver
- Spare Info Basic spare drive information
- Spare Dump Info Diagnostic information
- Spare Verbose Info Full spare Drive
   information
- Statistic Info
- Subsystem info
- User Info

# **EMAIL SERVICE**

Email service enables the RAID subsystem to send you Email messages about events and status changes. By default, Email service is set to Automatic.

# STOP EMAIL SERVICE

To stop the Email service:

- 1. Click the **Administrative Tools** icon.
- 2. Click the Software Management icon.
- 3. Click on Email in the Service List of the Service Management menu.
- 4. Click the Stop button under Service Status -- Email.
- 5. Click the **Confirm** button.

To start the Email service after stopping it:

- 1. Click the Administrative Tools icon.
- 2. Click the **Software Management** icon.
- 3. Click on **Email** in the Service List of the Service Management menu.
- 4. Click the Start button under Service Status -- Email.
- 5. Click the **Confirm** button.

## **R**ESTARTING **E**MAIL **S**ERVICE

To restart the Email service:

- 1. Click the **Administrative Tools** icon.
- 2. Click the Software Management icon.
- 3. Click on **Email** in the Service List of the Service Management menu.
- 4. Click the **Restart** button under Service Status -- Email.
- 5. Click the **Confirm** button.

## **E**MAIL **S**ETTINGS

To change Email service settings:

- 1. Click the **Administrative Tools** icon.
- 2. Click the **Software Management** icon.
- 3. Click on **Email** in the Service List of the Service Management menu.
- 4. Make settings changes as required:

Under Service Setting -- Email choose a startup type:

- Automatic (default) Starts and runs with the subsystem.
- Manual You start the service when you need it.

#### Under Email Server Settings

- SMTP Server IP address
- SMTP Authentication under *Email Server Settings* The Yes option enables authentication. The No option disables.
- SMTP Authentication under *Email Server Settings* Username Required if SMTP authentication is enabled.
   SMTP Authentication Password Required if SMTP authentication is enabled.

#### Under Email Content Customization

- Email Sender (From) Address The sender's name shown on notification messages.
- Email Subject The subject line of the notification message.
- 5. Click the **Submit** button.
- 6. Click the **Confirm** button.

## Sending A Test Email Message

After email settings are completed, you can send a test email.

To send a test email message, complete email settings as described above and check the Send a test email

option box, then click the **Submit** button. A test email message is sent to the address you specified.

### **Performance Monitoring**

The Performance Monitor displays real-time performance statistics for logical drives and physical drives. The vertical scale adjusts dynamically to accommodate the statistical data.

Because it reports performance in real-time, to see data in the monitor, there must be I/O data activity taking place between the subsystem and the Host.

To monitor performance:

- 1. Click the **Administrative Tools** icon.
- 2. Click the Performance Monitoring icon.
- Click the Information tab for aggregated statistics; or choose the Read/Write tab to view specific Read and Write performances separately.
- 4. Under Logical Drive, choose the metric you want to see from the Measurement drop-down menu.

#### Information

- Bandwidth in MB/s
- Cache usage by %
- Dirty cache usage by %
- Maximum latency in ms
- Average latency in ms
- Minimum latency in ms
- I/Os per second

#### Read/Write

- Read bandwidth
- Write bandwidth
- Maximum Read latency in ms
- Maximum Write latency in ms
- Average Read latency in ms
- Average Write latency in ms
- Minimum Read latency in ms
- Minimum Write latency in ms
- Write Regs
- Read Regs
- 5. Check the boxes for the logical drives you want to see.
  - Total of all logical drives
  - Up to 4 devices

6. Under Physical Drive, choose the metric you want to see from the Measurement drop-down menu.

Information

- Bandwidth in MB/s
- Maximum latency in ms
- Average latency in ms
- Minimum latency in ms
- I/Os per second

#### Read/Write

- Read bandwidth
- Write bandwidth
- Maximum Read latency in ms
- Maximum Write latency in ms
- Average Read latency in ms
- Average Write latency in ms
- Minimum Read latency in ms
- Minimum Write latency in ms
- Write Regs
- Read Regs

7. Check the boxes for the physical drives you want to see.

- Total of all physical drives
- Up to 4 devices
- I/Os per second

Since the performance monitor is a real-time display, it does not accumulate information and there is no clear or save function.

To save performance statistics for analysis or troubleshooting, save a Service Report. See "Saving a Service Report".

## CONTROLLERS

Click on a specific controller in Tree view to display information or statistics for a controller. Or to change

controller settings. See the following sections:

- "View Controller Information"
- "Viewing Controller Statistics"
- "Controller Settings"

## **VIEW CONTROLLER INFORMATION**

To view controller information:

- 1. Click the **Controllers** icon.
- 2. Click the specific **Controller** icon of the controller for which you want to view information.
- 3. The Information tab will present basic controller information.

Controller information includes:

- Controller ID
- Alias
- Operational Status
- Power on Time
- Cache Usage
- Dirty Cache Usage
- Part Number

- Serial Number
- Hardware Revision
- WWN
- SCSI Protocols Supported
- Install Package Version
- Install Package Build Date

1. Click the **Advanced Information** menu expander to view advanced information.

Advanced controller information includes:

- Memory Type
- Memory Size
- Flash Type
- Flash Size
- Preferred Cache Line Size
- Cache Line Size
- Coercion Enabled/Disabled\*
- Coercion Method\*
- SMART Log Enabled/Disabled\*
- SMART Polling Interval \*

- Write Back Cache Flush Interval\*
- Enclosure Polling interval
  - Host Cache Flushing Enabled/Disabled\*
- Forced Read Ahead Enabled/Disabled\*
- Spin Down Type

•

- HDD Power Levels\*
- HDD Idle Time\*
- HDD Standby Time\*
- HDD Stopped Time\*
- Physical Drive Temperature Threshold\*
- Physical Drive Critical Temperature Threshold\*

Items with an asterisk (\*) are adjustable under Controller Settings.

## **VIEWING CONTROLLER STATISTICS**

To view controller statistics:

- 1. Click the **Controllers** icon.
- 2. Click the specific **Controller** icon of the controller for which you want to view statistics.
- 3. At the top of the Information display menu, between the Information and Settings tabs, click on the menu expander to reveal the Statistics link.

Controller statistics include:

- Data Transferred
- Read Data Transferred
- Errors
- Read Errors
- I/O Requests
- Read IO Requests
- Statistics Start Time

- Write Data Transferred
- Non-Read/Write Errors
- Write Errors
- Non-Read/Write Requests
- Write I/O Requests
- Statistics Collection Time

## **CONTROLLER SETTINGS**

To make controller settings:

- 1. Click the **Controllers** icon.
- 2. Click the specific **Controller** icon of the controller you want to manage.
- 3. Click the **Settings** tab.
- 4. Make settings changes as required:
  - Enter, change or delete the alias in the **Alias** field.
  - **Coercion** Check the box to enable or uncheck to disable.
  - **Coercion Method** Choose a method from the drop-down menu:

GBTruncate

10GBTruncate

GrpRounding

TableRounding

- Write Back Cache Flush Interval Enter a value into the field, 1 to 12 seconds.
- **HDD Power Saving** Choose time periods from the drop-down menus. After an HDD has been idle for the set period of time:

Power Saving Idle Time – Parks the read/write heads.

**Power Saving Standby Time** – Lowers disk rotation speed.

Power Saving Stopped Time – Spins down the disk (stops rotation).

- Host Cache Flushing Check the box to enable or uncheck to disable.
- Forced Read Ahead (cache) Check the box to enable or uncheck to disable.
- Physical Drive Temperature Threshold Type a temperature (50-55 °C) to trigger an event notice and email alert.
- Physical Drive Critical Temperature Threshold Type a temperature (58-65 °C) to trigger system shutdown.
- 5. Click the **Submit** button.

## **E**NCLOSURES

The Enclosure menus are used to provide information for and monitor the status about the various components of the enclosure unit. Click on a specific enclosure in Tree view or in the Enclosures list to display information or settings menus for an enclosure. See the following sections:

- "Enclosure Information"
- "Enclosure temperature sensor settings"
- "Buzzer Settings"
- "Physical Drives"

#### LOCATE AN ENCLOSURE

To locate an enclosure in the list, click the **Locate** button. The LED indicators on the front panel of the enclosure will blink for one minute.

### **ENCLOSURE INFORMATION**

The Enclosure Information read-only display menu provides key real-time information about current hardware status of the enclosure. Click on the expanders buttons to reveal current conditions and status of the enclosure, power supplies, fans, blowers, temperature sensors and voltage sensors. Move the cursor over the icons in the virtual enclosure displayed at the top of the menu to see current status and relevant conditional statistics for the fans, power supplies, and temperature sensors.

#### Enclosure Information display

Home (User: administrator)	Enclosure Information		Help
Subsystems Incalhost (Vess A6800)	Information Settings Buzzer	<b>~</b>	
ddministrative Tools     ddministrative Tools     Controllers     Enclosures     Enclosure 1     Drysical Drives     Jisk Arrays	Enclosure Back View		
Logical Drive Summary	S Enclosure Information		
	Enclosure ID	1	
	Enclosure Type		
	Enclosure Type	ENC_TYPE_VA6800_4U24BAY	
	Controller Warning Temperature Threshold	ENC_1YPE_VA0800_4024BAY 80°C / 176°F	
	Controller Warning Temperature		
	Controller Warning Temperature Threshold Controller Critical Temperature	80°C / 176°F	
	Controller Warning Temperature Threshold Controller Critical Temperature Threshold	80°C / 176°F 100°C / 212°F	
	Controller Warning Temperature Threshold Controller Critical Temperature Threshold Max Number of Controllers	80°C / 176°F 100°C / 212°F 1	
	Controller Warning Temperature Threshold Controller Critical Temperature Threshold Max Number of Controllers Max Number of Physical Drive Slots	80°C / 176°F 100°C / 212°F 1 24	
	Controller Warning Temperature Threshold Controller Critical Temperature Threshold Max Number of Controllers Max Number of Physical Drive Slots Max Number of Fans	80°C / 176°F 100°C / 212°F 1 24 0	
	Controller Warning Temperature Threshold Controller Critical Temperature Threshold Max Number of Controllers Max Number of Fans Max Number of Fans Max Number of Blowers	80°C / 176°F 100°C / 212°F 1 24 0 5	

### **E**NCLOSURE TEMPERATURE SENSOR SETTINGS

The temperature threshold settings are used to send event notices when the internal temperature reaches a high level. To set enclosure temperature thresholds, click on the enclosure in Tree View, then click on the

Settings tab to view the Enclosure Settings menu. There are two thresholds to configure:

- Controller Warning Temperature Threshold [80-95 C°] If the enclosure temperature reaches this threshold, a warning message is sent and an event is recorded in the event log.
- Controller Critical Temperature Threshold [100-105 C°] If the enclosure temperature reaches this threshold, a warning message is sent, an event recorded is recorded in the event log.

### **B**UZZER **S**ETTINGS

The audible enclosure alarm buzzer can be enabled or disabled.

To enable or disable the buzzer, click on the enclosure in Tree View, then click on the Buzzer menu expander,

scroll to Settings and click the check Enable Buzzer option box. Click the Submit button.

## **PHYSICAL DRIVES**

The Physical Drives menus are used to view information and statistics about physical hard drives installed in the enclosure and to set Global Settings for hard drives. To see the Physical Drives List, expand the individual Enclosure icon in Tree View to see the Physical Drives icon for the enclosure. To display the information for any populated slot, you can expand the Physical Drives icon in Tree View to reveal links to each slot, or click on the slot in the Physical Drives List, or click on the populated slot in the virtual enclosure displayed in the menu.

ome (User: administrator)	Physical Driv	res					
Subsystems	Information (	Global Settings					
i localhost (Vess A6800)	Information	alobal Settings					
👜 🛒 Administrative Tools	▼ Enclosure Fr	ont View					
Controllers							
Enclosures							
Enclosure 1							
Physical Drives							
Slot 1: TOSHIBA MC04A			0				
Slot 2: TOSHIBA MC04A		Enclosure 1					
Slot 3: TOSHIBA MC04A		Literative x					
Slot 4: TOSHIBA MC04A							
Slot 5: TOSHIBA MC04A							
Slot 6: TOSHIBA MC04A							
Slot 7: TOSHIBA MC04A							
Slot 8: TOSHIBA MC04A				Click a drive to	locate.		
Slot 9: TOSHIBA MC04A							
Slot 10: TOSHIBA MC04.	Physical Driv	ve List					
Slot 11: TOSHIBA MC04.	Device	Model	Type	Configurable Capacity	Location	Operational Status	Configuration Status
Slot 12: TOSHIBA MC04.	PD1	TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 1	OK	Revert Global Spare
Slot 13: TOSHIBA MC04.	PD2	TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 2	OK	Array0 SeqNo0
Slot 14: TOSHIBA MC04	PD3	TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 3	OK	Array0 SeqNo1
Slot 15: TOSHIBA MC04	PD4	TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 4	OK	Array0 SeqNo2
	PD5	TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 5	OK	Array0 SeqNo3
Slot 16: TOSHIBA MC04.	PD6	TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 6	OK	Array0 SeqNo4
Slot 17: TOSHIBA MC04.	PD7	TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 7	OK	Array0 SeqNo5
Slot 18: TOSHIBA MC04.	PD8	TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 8	OK	Array0 SeqNo6
Slot 19: TOSHIBA MC04.	PD9	TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 9	OK	Array0 SeqNo7
Slot 20: TOSHIBA MC04.	PD10	TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 10	OK	Array0 SeqNo8
Slot 21: TOSHIBA MC04.	PD11	TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 11	OK	Array0 SeqNo9
Slot 22: TOSHIBA MC04.	PD12 PD13	TOSHIBA MC04ACA500E TOSHIBA MC04ACA500E	SATA SATA	4.55TB 4.55TB	Encl 1 Slot 12 Encl 1 Slot 13	ок	Array0 SeqNo10
Slot 23: TOSHIBA MC04.	PD13 PD14	TOSHIBA MC04ACA500E TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 13 Encl 1 Slot 14	OK	Array0 SeqNo11 Array0 SeqNo12
Slot 24: TOSHIBA MC04	PD14 PD15	TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 14 Encl 1 Slot 15	OK	Array0 SeqNo12 Array0 SeqNo13
Disk Arrays	PD15	TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 15	OK	Array0 SeqNo13
TT I	PD10	TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 17	OK	Array0 SeqNo15
🗎 🧊 Disk Array 0	PD18	TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 18	OK	Array0 SeqNo15
Logical Drives	PD19	TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 19	OK	Array0 SegNo10
	PD20	TOSHIBA MC04ACA500E	SATA	4.55TB	End 1 Slot 20	OK	Arrav0 SegNo18
L. Logical Drive 0		TOSHIBA MC04ACA500E	SATA	4.55TB	Encl 1 Slot 21	OK	Array0 SeqNo19
Logical Drive 0	PD21				Encl 1 Slot 22	OK	
	PD21 PD22	TOSHIBA MC04ACA500E	SATA	4.55TB	Enci 1 5100 22	OK.	Array0 SeqNo20
B- G Spare Drives		TOSHIBA MC04ACA500E TOSHIBA MC04ACA500E	SATA SATA	4.55TB 4.55TB	Encl 1 Slot 22 Encl 1 Slot 23	OK	Array0 SeqNo20 Array0 SeqNo21

#### View individual physical drive information

The information listed for individual physical drives includes:

#### **Physical Drive Information**

- Physical Drive ID
- Location [Enclosure # Slot #]
- Alias
- Physical Capacity
- Configurable Capacity
- Used Capacity
- Block Size [Bytes]
- Operational Status

#### Advanced Physical Drive Information

- Write Cache [*Enabled/Disabled*]
- Read Look Ahead Cache [Enabled/ Disabled]
- SMART Feature Set
- SMART Self Test
- SMART Error Logging
- Command Queuing Support

- Configuration Status
- Model
- Drive Interface
- Serial Number
- Firmware Version
- Protocol Version
- Visible To [Controller #]

- Command Queuing [Enabled/Disabled]
- Queue Depth
- Maximum Multiple DMA Mode Supported
- Maximum Ultra DMA Mode Supported
- DMA Mode
- Drive Temperature [C°/F°]
- Reference Drive Temperature
- Power Saving Mode

## **DISK ARRAYS AND LOGICAL DRIVES**

Disk arrays and logical drives are created and managed using the **Disk Arrays** menu. Use the Array Configuration menu to view the Disk Array List, and to create and delete disk arrays on the enclosure. Expand the Disk Arrays icon in Tree View to view menu links for existing arrays. Each array icon can be expanded again to see the Logical Drives icon, and this can be expanded to see each logical drive icon.

For a detailed description of how to create disk arrays and logical drives using Promise Management GUI, please refer to the Quick Start Guide.

Use the top-level Disk Arrays menu to view the **Disk Array List**, to delete existing arrays, and to create new disk arrays using the Automatic, Express, or Advanced disk array creation menus. Note that there must be physical drives available in order to use any of the disk array creation menus.

View information for existing disk arrays by clicking on the icon in Tree View or the array name in the Disk Array List. Each individual array menu is used to create and delete logical drives, to change settings (Alias and start/ stop PDM, Media Patrol and Power Management) for the array, or to start Background Activities including PDM, Rebuild and Transition.

🚹 Home (User: administrator)	Disk Array 0				Help
Ubsystems	Information Settings	Create LD	Delete LD	Background Activities 🔻	
localhost (Vess A6800)	Enclosure Front View				
📮 🗾 Administrative Tools	<ul> <li>Enclosure Front view</li> </ul>				
Controllers					
🖬 🥃 Enclosures					
🖨 🧊 Disk Arrays					
🗎 🧊 Disk Array 0		9			
🖽 🗐 Logical Drives					
🗐 🍙 Spare Drives	Enclosure 1		╞┿╡╞━		
📕 🗐 Logical Drive Summary					
	<ul> <li>Disk Array Information</li> </ul>	n			
	Disk Array ID		0		
	Alias				
	Operational Status			К	
	Total Physical Capacity			04.61TB	
	Configurable Capacity			04.59TB	
	Free Capacity	nacity	0	Byte	
	Free Capacity Max Contiguous Free Ca	pacity	0	Byte Byte	
	Free Capacity Max Contiguous Free Ca Media Patrol	pacity	0 0 E	Byte Byte nabled	
	Free Capacity Max Contiguous Free Ca Media Patrol Drive Health Polling	pacity	0 0 E	Byte Byte	
	Free Capacity Max Contiguous Free Ca Media Patrol		0 0 E	Byte Byte nabled nabled	
	Free Capacity Max Contiguous Free Ca Media Patrol Drive Health Polling Power Management	es	0 0 E E	Byte Byte nabled nabled 3	

#### Individual Disk Array menu

Information in the Disk Array menu includes:

- Disk Array ID [#]
- Alias
- Operational Status (see below)
- Total Physical Capacity
- Configurable Capacity
- Free Capacity [Bytes]
- Max Contiguous Free Capacity [Bytes]

Other lists in this menu:

- Physical Drives in the Disk Array
- Logical Drives in the Disk Array
- Available Spare Drives to the Disk Array

- Media Patrol [Enabled/Disabled]
- Drive Health Polling
- Power Management [Enabled/Disabled]
- Number of Physical Drives
- Number of Logical Drives
- Available RAID Levels

#### Disk Array Operational Status

*OK* – This is the normal state of a logical drive. When a logical drive is Functional, it is ready for immediate use. For RAID Levels other than RAID 0, the logical drive has full redundancy.

*Synchronizing* – This condition is temporary. Synchronizing is a maintenance function that verifies the integrity of data and redundancy in the logical drive. When a logical drive is Synchronizing, it will function and your data is available. However, access will be slower due to the synchronizing operation.

*Critical / Degraded* – This condition arises as the result of a physical drive failure. A degraded logical drive will still function and your data is still available. However, the logical drive has lost redundancy (fault tolerance). You must determine the cause of the problem and correct it.

*Rebuilding* – This condition is temporary. When a physical drive has been replaced, the logical drive automatically begins rebuilding in order to restore redundancy (fault tolerance). When a logical drive is rebuilding, it will function and your data is available. However, access will be slower due to the rebuilding operation.

### LOGICAL DRIVE MANAGEMENT

Logical drives are made from disk arrays. In the Tree, you can see a graphic representation of the logical drives that belong to each array. The Logical Drive List can be accessed in Tree View by expanding the under Disk Arrays and clicking on the Logical Drives icon for any existing disk array, or simply click on the **Logical Drive Summary** icon for the Subsystem.

Click on any Logical Drive (LD) in the list to view Information and Statistics, to change Settings (Alias, Read Policy,Write Policy), to start Background Activities (Initialization, Redundancy Check), or to view the Check Table for the LD.

Information displayed in the menu includes:

- Logical Drive ID
- Alias
- Raid Level
- Operational Status
- Capacity
- Physical Capacity
- Number of Axles [#]
- Number of Used Physical Drives [#]
- Stripe Size
- Sector Size [Bytes]
- Disk Array ID

- Read Policy
- Write Policy
- Current Write Policy
- Serial Number
- WWN
- Synchronized [Yes/No]
- Tolerable Number of Dead Drives Per Axle
- Parity Pace
- Codec Scheme

## **S**PARE **D**RIVES

When a physical drive in a disk array fails and a spare drive of the same type and adequate capacity is available, the disk array will begin to rebuild automatically using the spare drive.

In Tree View, click on the Spar Drive icon to see the Spare Drives List, or to create or delete an existing spare drive. Click on any spare drive in the list to information about the drive. Spare Drive Information includes:

- Spare Drive ID
- Physical Drive ID
- Spare Type
- Revertible [Yes/No]
- Operational Status
- Spare Check Status
- Physical Capacity
- Configurable Capacity

#### **RUNNING SPARE CHECK**

A Spare Check verifies the operational status of your spare drives. You can also schedule a Spare Check.

To check a spare drive:

- 1. Click the Spare Drives icon.
- 2. Click the Spare Check tab.
- From the Physical Drive drop-down menu, choose the spare drive you want to check. Or choose All to check all the spare drives at the same time.
- 4. Click the **Submit** button.

The results of the Spare Check appear under Spare Check Status in the Information tab. "Healthy" means normal condition.

- Block Size
- Drive Interface
- Model
- Location
- Configuration Status
- Serial Number
- Firmware Version

## LOGICAL DRIVE SUMMARY

The Logical Drive Summary displays a list of all logical drives in the Subsystem. This list does not arrange the logical drives under the disk array to which they belong nor under the enclosure in which they are located. The menu functions in the same way as the Logical Drives menu discussed in "Logical drive management" on page 72

# MAINTENANCE

This chapter covers the following topics:

• "Replacing a Power Supply"

## **R**EPLACING A **P**OWER **S**UPPLY

The Vess A6600 systems can accommodate two AC power supplies in the bay at the rear of the chassis. The Vess A6800 systems can accommodate three AC power supplies in the bay at the rear of the chassis. Each unit provides up to 550 Watts of power. Only a single power supply is required for operation, with the second power supply purely as a redundant, load-sharing backup. It can be removed without affecting system operation.

Installing and Removing the Power Supply

- 1. Align the power supply unit with the power supply slot. Ensure that the LED appears on the left when you are installing the power supply unit.
- 2. Carefully slide the PSU all the way into the power supply bay until it clicks into place.

### **REMOVING THE POWER SUPPLY UNIT**

To remove a failed power supply, please first identify the failed power supply .

- 1. Hold onto the power supply handle while pressing the locking lever towards the power supply handle.
- 2. Pull to remove the power supply from the chassis.
  - 1. Before replacing the power supply, power off the server, unplug the power cord, and disconnect all wiring from the power supply.
  - 2. In a redundant system, you do not need to power down the server.

# TROUBLESHOOTING

This section focuses on how to address issues that might appear during the lifetime of the Vess A6000 enclosure. Common issues that customers might see include hard drive problems and how to know when there is a problem with a hard drive, and how to create and send a service report to technical support.

If a hard drive has errors, is about to fail or has already failed, it will need to be replaced. Follow the instructions in "Installing Disk Drives" on page 25 to swap out bad hard drives.

This chapter includes the following troubleshooting sections and related information:

- "How do I know when a drive is failing?"
- "How to Rebuild a Disk Array"
- "The Alarm Buzzer is Sounding, what does this mean?"
- "How to disable the alarm buzzer"
- "How to Save a Service Report"



Note

Hard drives on the Vess A6000 models can be hot swapped, that is, they can be replaced without first shutting down the system.



#### Note

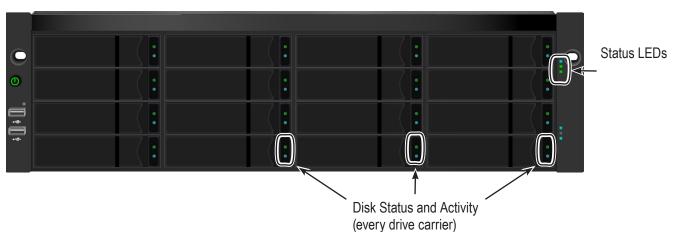
Follow the instructions in "Installing Disk Drives" on page 25 to swap out bad hard drives.

## How do I know when a drive is failing?

There are many options to determine the health of physical hard drives. In Web PAM PROe, you can either use the Event Frame or go to the Physical Drives information display. Or you can simply check the status LED of the drives on the device.

## CHECK DRIVE STATUS LEDS

The quickest way to check drive status if you are near the device is to simply look at the hard drive status LED indicators, then use the other LED indicators to help diagnose any problems that might exist.



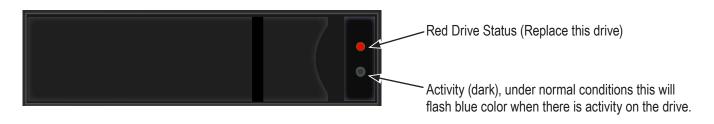
#### Vess A6600 front

#### Status LED behavior

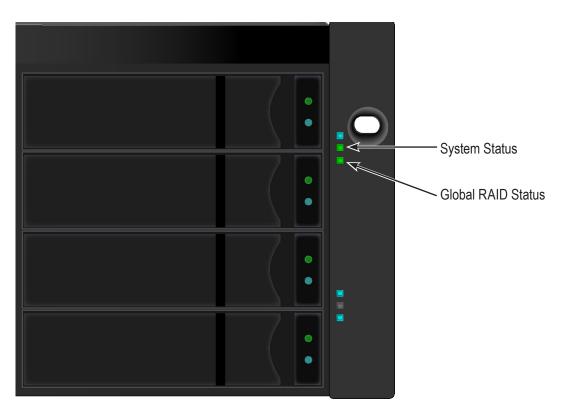
HDD Status	The Disk Status LED displays GREEN when a drive is configured and working properly. When the lights are RED the HDD requires manual replacement. When ORANGE is ob- served it indicates background RAID activity on this particular HDD and no user action is required.
System Status	Lights GREEN when healthy, RED if there is a critical problem (LD offline, fan malfunc- tion, voltage out of range, system temperature alert), blinks RED for HDD high tempera- ture alert remains dark when not ready. This will be RED if a hard drive has failed or has critical errors. Replace the drive corresponding to the RED HDD Status indicator.
	Lights GREEN when healthy or RED if any RAID volume is offline, ORANGE for critical state of any logical drive. If a hard drive has failed, this will be ORANGE. In this case, it will be necessary to replace the affected drive and rebuild the affected RAID volume.

The Vess A6000 models have hard drive status and activity LEDs on each drive carrier. Also check the status indicators on the right side of the front of the device for clues about what is wrong.





#### Vess A6800 status LEDs on right side of front



#### CHECK DRIVE STATUS IN MANAGEMENT GUI

To see the Event Frame, click **Show Event Frame** in the Web PAM PROe Header and check the list under **Device**, any physical drive problems will be indicated in the right most column, the top rows of the event table list the installed physical drives.

Also, in Management GUI, you can go to the **Physical Drives List**. To see the Physical Drives List, expand the individual Enclosure icon in Tree View to see the Physical Drives icon for the enclosure. To display the information for any populated slot, you can expand the Physical Drives icon in Tree View to reveal links to each slot, or click on the slot in the Physical Drives List, or click on the populated slot in the virtual enclosure displayed in the menu.

#### View physical drive list

Yenne (User: administrator)	Disk Array 0		Help
l-11 Subsystems 	Information Settings Create LD	Delete LD Background Activities	
🖬 🗾 Administrative Tools	Enclosure Front View		
Controllers  Cont			
<ul> <li>B ← Logical Drives</li> <li>□ ← → ← → ← → ← → ← → ← → ← → ← → ← → ←</li></ul>	Enclosure 1		
		sed by the array are highlighted. Click one of them to locate the array.	
	Disk Array Information		
	Disk Array ID	0	
	Alias		
	Operational Status	OK	
	Total Physical Capacity	104.61TB	
	Configurable Capacity	104.59TB	
	Free Capacity	OByte	
	Max Contiguous Free Capacity Media Patrol	OByte Enabled	
	Media Patrol	Enabled	
	Drive Health Belling	Epobled	
	Drive Health Polling	Enabled	
	Power Management	Enabled	

			Last Event: 121, LD 0, Info, Sep 19, 2018 18:12:58 Quick Logical drive initialization has completed
ome (User: administrator)	Physical Drive 1		н
Subsystems			
Docalhost (Vess A6800)	Information 🔻 Settings		
1	Enclosure Front View		
Administrative Tools     Controllers			
Enclosures			
Enclosure 1			
Physical Drives			
Slot 1: TOSHIBA MCO			
Slot 2: TOSHIBA MC0	Enclosure 1		
Slot 3: TOSHIBA MC0			
Slot 4: TOSHIBA MC0			
- Slot 5: TOSHIBA MCO			
Slot 6: TOSHIBA MC0			
Slot 7: TOSHIBA MCO			
		Current drive location is highlighted. To choose a new drive click on the desired location	ion.
Slot 9: TOSHIBA MC0			
Slot 10: TOSHIBA MC	<ul> <li>Physical Drive Information</li> </ul>		
Slot 11: TOSHIBA MC	Physical Drive ID	1	
	Location	Enclosure 1 Slot 1	
Slot 12: TOSHIBA MC			
Slot 12: TOSHIBA MC	Alias		
Slot 13: TOSHIBA MC	Physical Capacity	4.55TB	
- Slot 13: TOSHIBA MC - Slot 14: TOSHIBA MC	Physical Capacity Configurable Capacity	4.55TB	
	Physical Capacity Configurable Capacity Used Capacity	4.55TB 0Byte	
-Slot 13: TOSHIBA MC Slot 14: TOSHIBA MC Slot 15: TOSHIBA MC Slot 15: TOSHIBA MC Slot 16: TOSHIBA MC	Physical Capacity Configurable Capacity Used Capacity Block Size	4.55TB OByte 512 Bytes	
- Slot 13: TOSHIBA MC Slot 14: TOSHIBA MC Slot 15: TOSHIBA MC Slot 16: TOSHIBA MC Slot 16: TOSHIBA MC	Physical Capacity Configurable Capacity Used Capacity Block Size Operational Status	4.55TB 0Byte 512 Bytes OK	
Slot 13: TOSHIBA MC Slot 14: TOSHIBA MC Slot 15: TOSHIBA MC Slot 16: TOSHIBA MC Slot 16: TOSHIBA MC Slot 17: TOSHIBA MC	Physical Capacity Configurable Capacity Used Capacity Block Size Operational Status Configuration Status	4.5STB 0Byte 512 Bytes OK Revert Global Spare	
Slot 13: TOSHIBA MC Slot 14: TOSHIBA MC Slot 15: TOSHIBA MC Slot 16: TOSHIBA MC Slot 16: TOSHIBA MC Slot 17: TOSHIBA MC Slot 19: TOSHIBA MC	Physical Capacity Configurable Capacity Used Capacity Block Size Operational Status Configuration Status Model	4.5STB OByte 512 Bytes OK Revert Global Spare TOSHIBA MC04ACA500E	
Slot 13: TOSHIBA MC Slot 14: TOSHIBA MC Slot 15: TOSHIBA MC Slot 16: TOSHIBA MC Slot 16: TOSHIBA MC Slot 17: TOSHIBA MC	Physical Capacity Configurable Capacity Used Capacity Block Size Operational Status Configuration Status	4.5STB 0Byte 512 Bytes OK Revert Global Spare	
Slot 13: TOSHIBA MC Slot 14: TOSHIBA MC Slot 15: TOSHIBA MC Slot 16: TOSHIBA MC Slot 16: TOSHIBA MC Slot 17: TOSHIBA MC Slot 19: TOSHIBA MC	Physical Capacity Configurable Capacity Used Capacity Block Size Operational Status Configuration Status Model Drive Interface	4.55TB OByte 512 Bytes OK Revert Global Spare TOSHIBA MC04ACA500E SATA 6Gb/s	
Slot 13: TOSHIBA MC Slot 14: TOSHIBA MC Slot 15: TOSHIBA MC Slot 16: TOSHIBA MC Slot 16: TOSHIBA MC Slot 17: TOSHIBA MC Slot 19: TOSHIBA MC Slot 20: TOSHIBA MC	Physical Capacity Configurable Capacity Used Capacity Block Size Operational Status Configuration Status Model Drive Interface Serial Number	4.55TB OByte 512 Bytes OK Revert Global Spare TOSHIBA MC04ACA500E SATA 6Gb/s 84B3K01YFLRA	
Slot 13: TOSHIBA MC Slot 14: TOSHIBA MC Slot 15: TOSHIBA MC Slot 16: TOSHIBA MC Slot 17: TOSHIBA MC Slot 18: TOSHIBA MC Slot 19: TOSHIBA MC Slot 20: TOSHIBA MC Slot 20: TOSHIBA MC	Physical Capacity Configurable Capacity Used Capacity Block Size Operational Status Configuration Status Model Drive Interface Serial Number Firmware Version	4.5STB 0Byte 512 Bytes OK Revert Global Spare TOSHIBA MC04ACA500E SATA 6Gb/s 8483K01YFLRA FP2A	
Slot 13: TOSHIBA MC Slot 14: TOSHIBA MC Slot 15: TOSHIBA MC Slot 15: TOSHIBA MC Slot 16: TOSHIBA MC Slot 17: TOSHIBA MC Slot 19: TOSHIBA MC Slot 21: TOSHIBA MC Slot 21: TOSHIBA MC	Physical Capacity Configurable Capacity Used Capacity Block Size Operational Status Configuration Status Model Drive Interface Serial Number Firmware Version Protocol Version Visible To	4.5STB OByte 512 Bytes OK Revert Global Spare TOSHIBA MC04ACA500E SATA 6Gb/s 84B3K01YLRA FP2A ATA/ATAPI-8	
Slot 13: TOSHIBA MC Slot 14: TOSHIBA MC Slot 15: TOSHIBA MC Slot 15: TOSHIBA MC Slot 16: TOSHIBA MC Slot 17: TOSHIBA MC Slot 19: TOSHIBA MC Slot 20: TOSHIBA MC Slot 20: TOSHIBA MC Slot 22: TOSHIBA MC Slot 22: TOSHIBA MC	Physical Capacity Configurable Capacity Used Capacity Block Size Operational Status Configuration Status Model Drive Interface Serial Number Firmware Version Protocol Version	4.5STB OByte 512 Bytes OK Revert Global Spare TOSHIBA MC04ACA500E SATA 6Gb/s 84B3K01YFLRA FP2A ATA/ATAPI-8	
Slot 13: TOSHIBA MC     Slot 14: TOSHIBA MC     Slot 15: TOSHIBA MC     Slot 15: TOSHIBA MC     Slot 16: TOSHIBA MC     Slot 17: TOSHIBA MC     Slot 18: TOSHIBA MC     Slot 19: TOSHIBA MC     Slot 20: TOSHIBA MC     Slot 21: TOSHIBA MC     Slot 22: TOSHIBA MC     Slot 23: TOSHIBA MC     Slot 23: TOSHIBA MC	Physical Capacity Configurable Capacity Used Capacity Block Size Operational Status Configuration Status Model Drive Interface Serial Number Firmware Version Protocol Version Visible To	4.5STB OByte 512 Bytes OK Revert Global Spare TOSHIBA MC04ACA500E SATA 6Gb/s 84B3K01YFLRA FP2A ATA/ATAPI-8	Activate

#### View individual physical drive information



Note

In order that hard disk problems can be anticipated and dealt with smoothly, it is highly recommended to make sure that Media Patrol is enabled and running and Auto Rebuild is enabled if you are not using a spare drive. If using a spare drive, make sure it is healthy and available.

## ANTICIPATING HARD DRIVE PROBLEMS

It is recommended that you always keep a healthy spare drive installed, and run Media Patrol as a background

activity so a failing hard drive can migrate data to the spare before the status turns critical.

In Web PAM PROe, Media Patrol is enabled or disabled using the Background Activities menu, you can also

create a schedule to run Media Patrol.

#### Enable Media Patrol

Home (User: administrator)	Background Activities	Hel
l 🎁 Subsystems	Information Settings Event V Background Activities V Scheduler V Lock	
🖨 间 localhost (Vess A6800)		
💷 🗾 Administrative Tools	Background Activity Settings	
🛱 🚍 Controllers	Rebuild Rate High	
Enclosures	Background Synchronization Rate	
Enclosure 1	Logical Drive Initialization Rate	
Disk Arrays	Redundancy Check Rate Medium	
Disk Array 0	Migration Rate	
Logical Drives	PDM Rate High V Transition Rate	
Logical Drive 0	Televin Account and a second an	
Spare Drives	Error Block Threshold [1-2048] 32 Blocks	
🖬 🗐 Logical Drive Summary	Enable Media Patrol	
	Reset Submit Cancel	

- To enable Media Patrol, click on *Background Activities* in the Quick Links menu in the Home page, or, click on the *Subsystem* in Tree View then click on the *Background Activities* menu tab, click the expander to the right of the tab and select the *Settings* option from the pull down menu. Click to check the *Enable Media Patrol* option. Notice also that the *Auto Rebuild* option is here as well. If you want to automatically begin rebuilding a logical drive as soon as a faulty drive is replaced, make sure this option is enabled.
- To begin running Media Patrol manually, click on the menu expander to the right of the Background Activities tab and scroll down and select *Start Media Patrol* to see the Start Media Patrol menu. Then click on the **Start** button.
- To schedule Media Patrol, click on the menu expander to the right of the Scheduler tab and scroll down and select *Add Media Patrol Schedule* to open the schedule menu. Use this menu to add a Media Patrol schedule.

### **R**EBUILDING A **D**ISK **A**RRAY

When you rebuild a disk array, you are actually rebuilding the data on one physical drive.

- When a physical drive in a disk array fails and a spare drive of adequate capacity is available, the disk array begins to rebuild automatically using the spare drive.
- If there is no spare drive of adequate capacity, but the Auto Rebuild function is ENABLED, the disk array begins to rebuild automatically as soon as you remove the failed physical drive and install an unconfigured physical drive in the same slot. See "Making Rebuild Settings"
- If there is no spare drive of adequate capacity and the Auto Rebuild function is DISABLED, you must replace the failed drive with an unconfigured physical drive, then perform a Manual Rebuild.

### How to **R**EBUILD A **D**ISK **A**RRAY

When a physical drive is indicated to be degraded or in critical state, the array that contains that drive needs to be rebuilt. If you are not using Auto Rebuild (requires a Spare Drive), then you must rebuild the array manually after the affected drive has been replaced. Follow the instructions here to rebuild an array.

You will know that a logical drive is critical by looking at the **Operational Status** in the **Logical Drive Information** display.

🕂 Home (User: administrator)	Logical D	rives							Help
Subsystems	Information	Drive List (2 Lo	vaical Drives)						
Administrative Tools Controllers				0	01-1-1	out-	Castar	Desferred Controller TD	On and the state
	Device	Alias	Raid Level	Capacity	Disk Array ID	Stripe	Sector	Preferred Controller ID	Operational Status
Enclosures	LD0		RAID6	45.47TB	0	64KB	512Bytes	N/A	Critical
🗖 🗊 Disk Arrays	LD1		RAID6	40.93TB	1	64KB	512Bytes	N/A	Synchronizing

#### Logical Drive Information

To begin rebuilding the drive, go to the *Local Host* menu, the **Background Activities** and move the cursor to select *Start Rebuild*. A new menu appears.

#### Background Activities Help Amme (User: administrator) Information Settings Event 💌 Background Activities 💌 Scheduler 💌 Lock localhost (Vess A6800) Background Activity Settings Settings Administrative Tools Background Synchronization Rate Start Media Patrol Controllers Rebuild Rate ~ Enclosures Logical Drive Initialization Rate Start Rebuild dium ~ Enclosure 1 Redundancy Check Rate 🖬 🧊 Disk Arrays Start PDM Migration Rate 🚊 🗊 Disk Array 0 PDM Rate ~ Start Transition 🖬 🗐 Logical Drives Transition Rate dium Reassigned Block Threshold [1-512] Start Initialization Logical Drive 0 Blocks Error Block Threshold [1-2048] 🛱 🍙 Spare Drives Blocks Start Redundancy Check Logical Drive Summary Enable Media Patrol Enable Auto Rebuild 4 Submit Reset Cancel

#### **Background Activities - Start Rebuild 1**

Now determine the source and target for the rebuild. In the new menu, choose the **Source Physical Drive** and **Target Physical Drive** from the menus, and click on the **Submit** button.

A Home (User: administrator)	Start Rebuild									Help
Subsystems	Information	Settings	Event -	Packgroup	nd Activities	r Schedule	r 🗶 Lock			
i (Vess A6800)			Event v	backgroun	IU ACUVILIES	Schedule				
👜 🗾 Administrative Tools	Rebuild Param	ieters								
Controllers	Source Physical				ray 0 SeqNo 22					
Enclosures	Target Physical	Drive		ID	1: 4.55TB	```	<ul> <li></li> </ul>			
Enclosure 1					Res	et Su	bmit C	ancel		
Disk Arrays										
🗎 💦 Disk Array 0										
🕮 🙀 Logical Drives										
🖬 🛣 Logical Drive Summary										

Background Activities - Start Rebuild 2

The progress of the rebuild is displayed in the Background Activities information display.

A Home (User: administrator)	Background Activities	Help		
Subsystems	Information Settings Event 🔻 Background Ac	tivities 🔻 Scheduler 🔻 Lock		
🖬 🗾 Administrative Tools	Background Activities			
Controllers	PD1 - Rebuild	<mark>.0%</mark>		
Enclosures	Background Activity Parameters			
Physical Drives	Rebuild Rate	High		
Disk Arrays	Background Synchronization Rate	Low		
Disk Array 0	Logical Drive Initialization Rate	Medium		
	Redundancy Check Rate	Medium		
Example 2 Logical Drives	Migration Rate	High		
	PDM Rate	High		
🖶 📊 Logical Drive Summary	Transition Rate	Medium		
	Reassigned Block Threshold	32 Blocks		
	Error Block Threshold	32 Blocks		
	Media Patrol	Enabled		
	Auto Rebuild	Enabled		
	Last Media Patrol Start Time	Not Started		
	Last Media Patrol Stop Time	Not Stopped		

**Background Activities - Rebuild Status** 

## How to Save a Service Report

A Service Report is a detailed report covering the configuration and status of all components in your RAID system. A support technician or field engineer might request a service report for the purpose of diagnosis and troubleshooting.

🕂 Home (User: administrator)	Subsystem localhost	Help		
Subsystems	Information Settings Event V Background Activities	The Schedular The Lack		
localhost (Vess A6800)	Information Settings Event V Background Activities			
🛱 🗾 Administrative Tools	<ul> <li>Subsystem Information</li> </ul>			
Controllers	Alias			
Enclosures	Vendor	Promise Technology, Inc.		
Disk Arrays	Model	Vess A6800		
📕 🥶 Disk Array 0	Serial Number	0000000000		
Logical Drives	WWN	2000-0001-5500-0000		
Spare Drives	Part Number Revision Number	A1		
E E Logical Drive Summary	System Date & Time	Sep 19, 2018 18:25:40		
	Save System Service Report	Save		

#### Subsystem Information - Save Service Report

To save a system configuration file:

- Click on the Subsystem icon (IP address and device name) in Tree View to open the Subsystem Information display.
- 2. Click the Save button in the Save System Service Report row of the information display.

Information for the report is gathered and compiled. This action takes up to a few minutes, depending on the size of your RAID system.

 Determine where you want to store the file on the Host PC, then click the Save button in the pop-up menu.

The report saves to your Host PC as a compressed HTML file.

- 4. Double-click the downloaded file to decompress it.
- 5. Double-click the report to open it in your default browser.

Once you have the service report file, you can email it to a Technical Support representative.

The Service Report includes the following topics:

- About Report utility
- BBM Info Bad Block Manager
- BGA Summary Status and settings
- Buzzer Info
- Controller Info
- Disk Array Info
- Disk Array Dump info
- Disk Array Verbose Info
- Enclosure Info
- Error Table Info
- Event Info NVRAM
- Event Info Runtime
- LogDrive Info Basic logical drive information
- LogDrive Dump Info Diagnostic information
- Logical Drive Verbose Info Full logical drive information

- Network Info Virtual port
- Phydriv Info Basic physical drive information
- Phydriv Verbose Info Full physical drive
- SWMGT Info Software management
- Service Setting Email
- Service Setting Webserver
- Spare Info Basic spare drive information
- Spare Dump Info Diagnostic information
- Spare Verbose Info Full spare Drive
  information
- Statistic Info
- Subsystem info
- User Info

### THE ALARM BUZZER IS SOUNDING, WHAT DOES THIS MEAN?

When you first power-up the Vess A6000 system beeps twice to show normal operation.

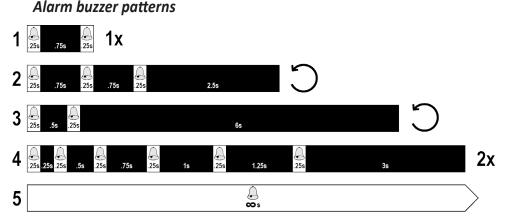
The audible alarm sounds at other times to inform you that the system needs attention. But the buzzer alarm is

not specific. Check the device LEDs and Events displays or logs for more information.

When the alarm sounds:

- Check the front and back of the enclosure for red or orange LEDs.
- If email notification is enabled, check for new messages.
- Check the event log.

When a continuous tone sounds, there are multiple alarm patterns sounding at the same time (see example number 1 illustrated below).



Other alarm patterns include three short buzzes followed by a longer silence, then repeated (example number 2 above). This can indicate a serious problem that requires immediate action such as high enclosure temperature or the system fan is not installed. If you hear this, check the System Status LED. If these are normal, it might indicate a physical drive problem, or a power supply problem. Check the event log for more information.

Pattern number 3 above might indicate an LD offline. Pattern number 4 might be an

LD critical or bad sector on a physical disk.

#### How to disable the alarm buzzer

To disable the buzzer with Web PAM PROe, open Web PAM PROe, click on the enclosure in Tree View, then click on the Buzzer menu expander, scroll to *Settings* and click the **Enable Buzzer** option box to remove the check mark. Click the **Submit** button.

# FAQ

#### Q: What is Vess A6000 Series Storage Appliance for Video Surveillance?

A: The Vess A6000 platforms are engineered specifically to be the best solution for midsize to large IP video surveillance deployments.

#### Q: How does it work for surveillance video recording?

A: The Vess A6000 comes complete with your choice of Windows OS, a leading Video Management Software suite, or Disk Drives, minimizing the integration and installation process. Users no longer need an extra PC/ server, add-on cards, or a separate connected storage for a complete video surveillance system; the Vess A6000 Series Storage Appliance for Video Surveillance does it all!

#### Q: What should I do if the device OS fails?

A: Unlike regular COTS servers that come with standard Windows OS, the Vess A6000 provides an embedded version that requires a certain process to rebuild the OS image. Users need to consult Promise tech support and follow installation guide to complete the setup.

#### Q: What's the standard warranty of Vess A6000?

A: We provide the same standard three (3) years hardware warranty from the time of the delivery of the product to the original end user.

#### Q: Can I purchase extended warranty package to Vess A6000?

A: Yes, we provide 2-year extended warranty program that uses the same order and support practice as Vess A6000 product series.

# Appendix: Driver Installation and Update

This appendix provides instructions for installing or updating the driver for the Promise RAID engine, as well as Management GUI, the management GUI for the Promise Vess A6000 Series.

Follow instructions in the ReadMe.txt file to install the latest hardware driver for the RAID and the latest Management GUI version.

## **UPDATE/INSTALLATION REQUIREMENTS**

#### USB FLASH DRIVE

A USB flash drive containing the update package is needed. Follow the instructions in the ReadMe.txt file to download the compressed file package and place a copy of the uncompressed file on the USB flash drive.

## UPDATE/INSTALL THE DRIVER

Follow instructions in the ReadMe.txt file for complete the installation or update of the driver.